

Purpose of testing

- * Testing is identifying the errors/bugs and checking against various test cases so as to check whether the program/software will work according to users requirements or not.
- * Myth: It is believed by developers who were expert in particular domain, that they could write error code.
Reality: But even in the code written by expert contains errors/bugs.
- * Generally it is assumed that there would be 1-3 bugs/errors for every 100 lines of code.

Productivity & quality in slw

- ▶ If the cost of rework exceeds 2% in smaller projects and if cost of rework exceeds 80% in big companies then the product must be destroyed of original cost.
- ▶ Only if above condition is met, then quality of product increases.

Goals of testing

Testing

Test design Testing

- ▶ prevention of bugs is not possible by test designer or testers but possible for designers.
- ▶ Secondary: discovery of bugs.
- ▶ Previous documentations help in preventing the similar mistakes to be made again.

Phases of Tester's mental life

- Phase 0: (until - 1956) - thinking - debugging
- Phase 1: (1957 - 1978) - demonstration - slw works oriented
- Phase 2: (1979 - 1982) - destruction - slw doesn't work
- Phase 3: (1983 - 1988) - risk reduction - evaluation
- Phase 4: (1989 - 2000) - prevention -

* until 1956 thinking and debugging are considered as testing, under one name only

- * The goal of software (1957 - 1978) was, there may be any number of bugs but finally a working product is developed called demonstration. (This failed because the probability of showing software works decreases as testing increases)
- * In 1983 - 1988, even there are a few bugs we cannot debug them. (at one bug to mention leads to another) These softwares come under this phase. (The purpose of these testing is to show the slw doesn't work)
- * An acceptable product is a product which is accepted by customer even though there are some bugs here and there.
- * Phase - 4, mostly type checking errors are present, which are rectified.

Testing isn't everything

- * even without testing, we can check the quality of software. (other approaches than testing to create better software)
- ① Inspection method: which involves formal inspections. we check whether the code meets the rules and regulations are not. In formal inspection, we check & verify the documentation after each phase of development [dash checking & code reading]
- ② Design style: The main objective of the product should be reflected in the design, which can be understood by any stakeholder. The features in the design must be unambiguous. (stability, openness & clarity prevents bugs)
- ③ Statistic Analysis design: (Compilers) whether the interpretation task which is done manually by programmers is efficient or not. Compilers were not existing at that time, it took more effort and accuracy in interpreting the code line by line. But the manually interpreting is very less efficient. (But now compilers have taken programmer's job)
- ④ Language: If the language supports various features and support it becomes easy to write error free code. (Programmers find new bugs when using new language)

And if the programmer is very good at a language, he can write efficient code

⑤ Development methodology & Development environment: The process model we choose and the deployment methods used to deploy programs improve the chance to rectify more bugs and produce a efficient working product.

Dichotomies → which involves various approaches for testing

① Testing & Debugging: until 1956 testing & debugging was considered as same, because the computers were not commercialized. But as the market grew for computers, testing and debugging were considered as separate. Test cases were chosen, in the parts where the input is taken and output is generated. Based on system we design which type of testing is needed (like unit testing, etc). We use predefined testing procedures and generate the predicted outputs. Debugging starts when the results are generated which were different from the predicted results / expected results. Debugging involves some corrections which may rise another issues. testing is time bound and need to be completed in time, but whereas debugging donot follow a definite procedure and every rectification must be documented as to know why certain things are changed. Testings can be automated, but debugging cannot be automated as one needs to constantly involve in project to debug, but testing can be done with minimal knowledge by anyone.

② Functional vs Structural: Functional testing mainly focuses on identifying the features are working according to the user requirements or not. Functional testing is similar to blackbox testing. Functional testing needs relatively large time. Structural testing mainly focusses on identifying whether the core implementation is working and also it focuses on implementation details and need small amount of time. [Functional testing can detect all bugs → takes infinite time. Structural testing can detect serious bugs → finite time.]

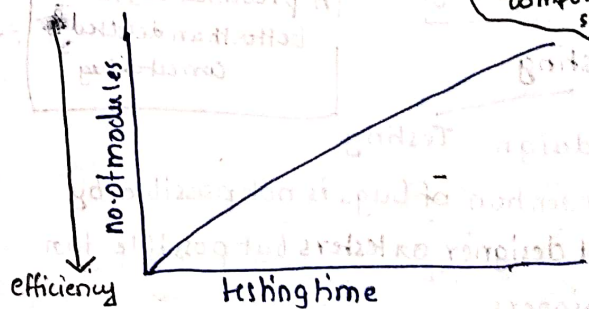
③ Designers vs Testers: Test designers | Designers work is to develop the test cases. Testers are one who actually implement the test case and test the code.

During functional testing designers take care different in functional testing tasks & programmer merge into one person.

④ large vs small large programs need relatively large amount of time for testing if it contains many modules - whereas small programs need less amount of time as they have lesser modules

⑤ modularity vs efficiency

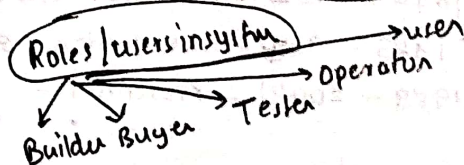
A module is a discrete well defined, small component of a system



⑥ Buyers vs Builder

Builders are the developers and buyers are customers. operators are responsible for the maintainance of the product / software

But if the buyer & builder are same, there will be no accountability

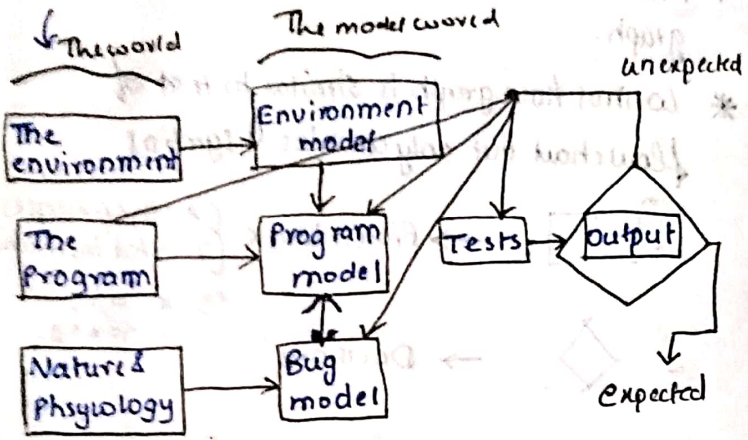


Model for Testing

There will be 3 models for the testing.

These three models can be combinedly called as the model for testing

- ① environment model
- ② program model
- ③ bug model



The environment: Software & hardware requirements to ~~run~~ a program. Ex: additional software

Program model: each person would have a different specialization in different languages. So, the modules are created by various persons but the entire project must be developed in a single language mostly.

And the way of representing bugs identified is called Optimistic of bugs

Optimistic ways of bugs

- ① Benign bug hypothesis
- ② Bug locality hypothesis
- ③ Control dominance
- ④ Code/data separation
- ⑤ Lingua saluator est
- ⑥ Correction abide
- ⑦ Silver Bullets
- ⑧ Angelic testes
- ⑨ Sadism Suffices

And a bug detected can be inidious (deceiving but harmful)

bug is not a serious issue

bug of one component does not affect other

one bug donot affect other

bug present in the control statement will be dominating the other bugs.

steps not on realization

rest → established

Tough bugs need methodology & techniques

Unethical arguments made by testers against developers

Identifying system & semantic error

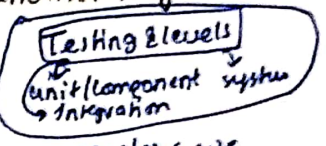
Some bugs cannot be corrected because it changes the core logic

Testing has to be happened based on values & ethics.

Testers should be more knowledgeable than developers

Consequences of Bugs

- * It involves the calculation of cost for bug identification based on bug frequency
- * Correction cost = discovery cost + debugging cost
- * Installation cost → If any additional components/ plugins are needed
- * One bug may lead to another bug called Consequence of bugs



based on these 4 parameters we decide which bugs should be resolved first.

$$\text{Importance of bug} = \$ = \text{Frequency} * (\text{Correction cost} + \text{Installation cost} + \text{Consequence cost})$$

> If there are no additional components needed and no consequence of bugs, there too can be removed from above formula

Scaling of bugs

Consequence of bugs

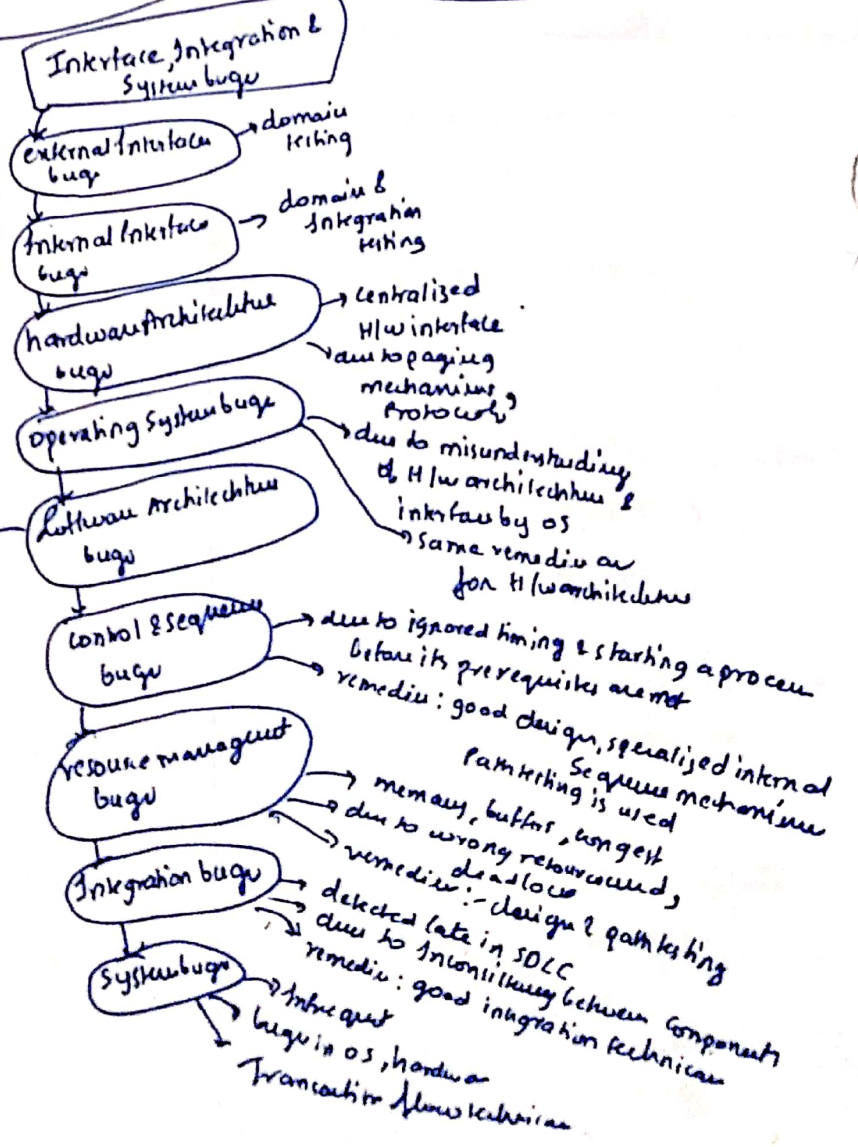
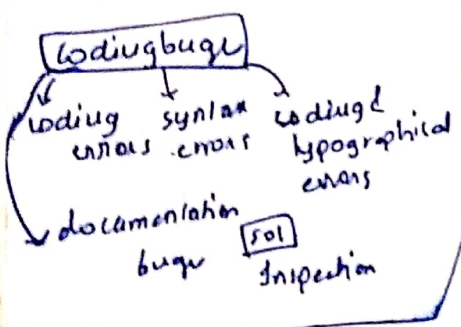
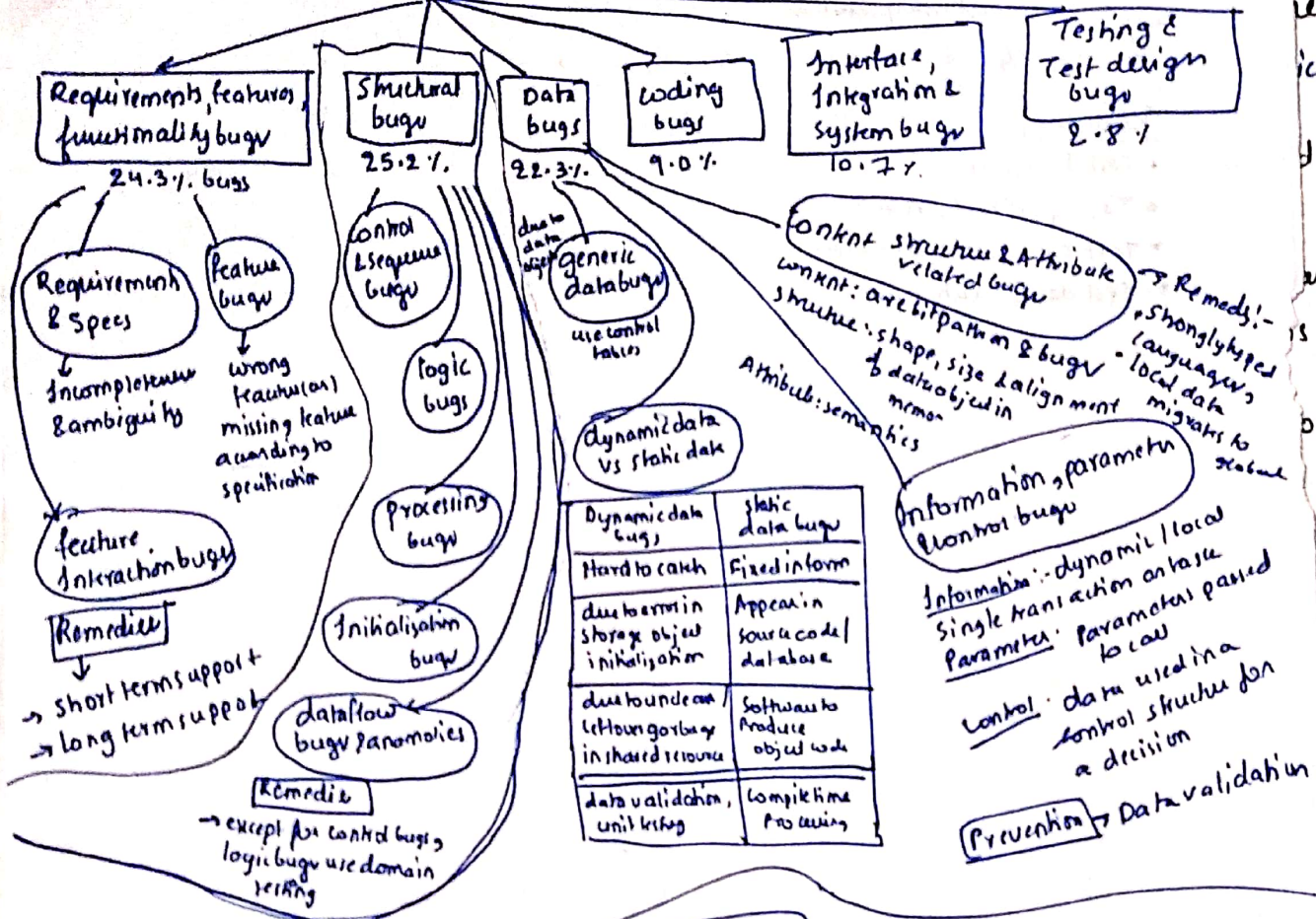
- ① Mild → A little → symptoms of bug offend us asymmetrically
- ② moderate → will affect the project → outputs are misleading or redundant
- ③ Annoying → will affecting a component → systemi behaviour is affected by bug
- ④ Disturbing → will affect a lot → it refers to handle legitimate transactions (eg: ATM)
- ⑤ serious → will cause errors → Accountability is lost as it loses track of its transactions
- ⑥ very serious → will cause crashes → This will cause systems to do wrong transactions
- ⑦ extreme → entire program crashes
- ⑧ Intolerable → Program will be non functional long term intolerable corruption
- ⑨ Catastrophic → Program doesn't load decision to shutdown is not an hands system fails
- ⑩ Inidious → high level. → that erodes social physical environment

Taxonomy of bugs

- ① Requirement, Features & functionality bugs
- ② Features bugs
- ③ Features Interaction bugs
- ④ Remedies for requirement specification future bugs & future Interaction bugs.

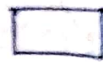
language grants immunity from bugs

Taxonomy of the bugs



Path testing → It is one of the oldest & structuring testing methods.

- * It is suitable for latest software
- * In path testing, mainly in which unit testing is done for a module
- * And the flow chart is converted into control flow graph.
- * Control flow graph is similar to that of flow chart but only contains 4 symbols



→ Process block

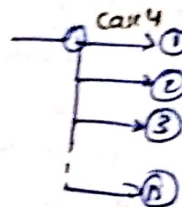
(All the process related instructions)
eg: int a; sum = a; sum = a + b;



→ Decisions



→ merge



→ care

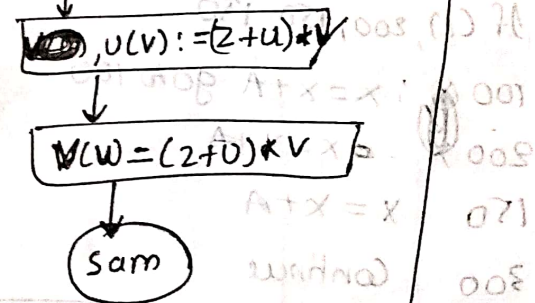
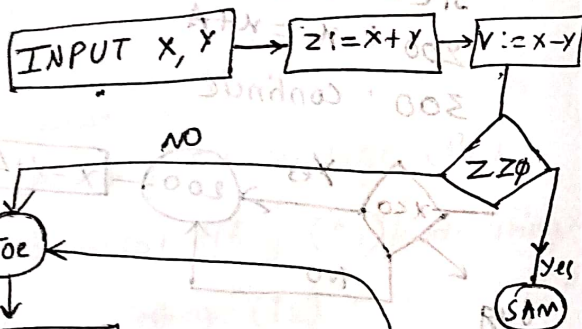
* And we can consider decision & connectors as a node.

write a program to find reverse of a number

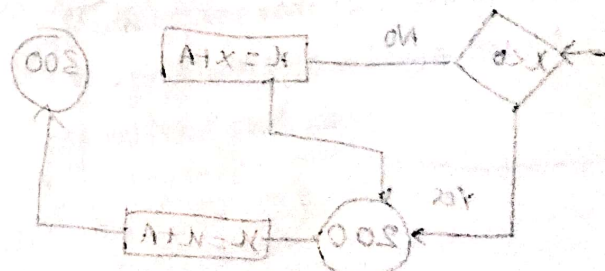
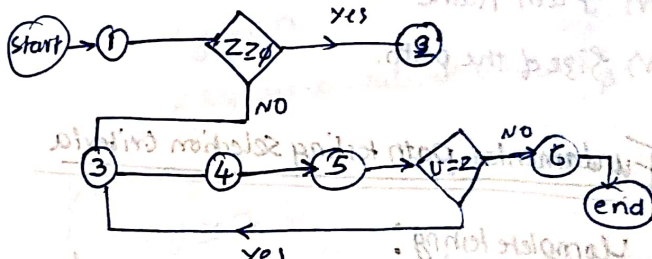
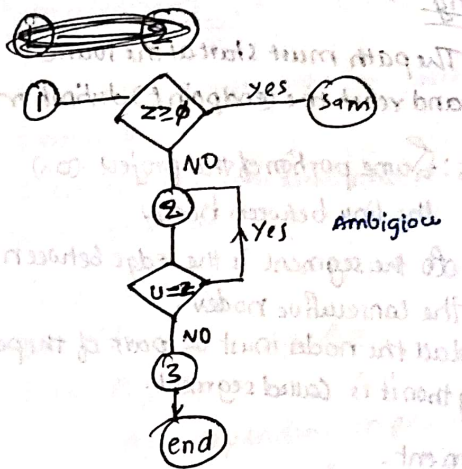
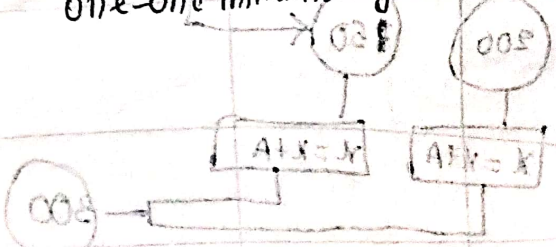
```

main()
{
    int n, x; char ch[10]; int d = 10;
    read n, x;
    for (i = 0; i < n; i++)
    {
        ch[i] = x % d;
        d = d * 10;
    }
    char rev[10];
    for (i = 0; i < n; i++)
    {
        rev[i] = ch[n-i-1];
        rev[i] = ch[j];
    }
}
    
```

ex: INPUT X, Y
 $Z := X + Y$
 $V := X - Y$
 IF $Z \geq 0$ GOTO SAM
 JOE: $Z := Z + 1$
 $V(U), U(V) := (Z + U) * V$
 SAM: IF $U = Z$ GOTO JOE
 $Z := 0$
 END



one-one instruction flow chart.



control flow graph for below program

300 : 000
 200 : 000
 100 : 000

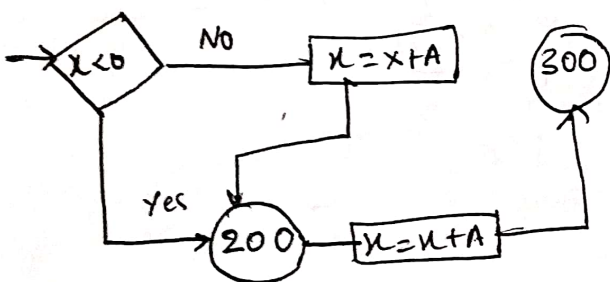
Path Testing

- (i) Path: The path must start at the source and reach the (endpoint) destination.
- (ii) Segment: Some portion of the project (or) the link between nodes.
 o the segment is the edge between the consecutive nodes.
 And all the nodes must be part of the path only then it is called segment.
- (iii) Path segment.
- (iv) Path name.
- (v) Size of the path.

Fundamental path testing selection criteria

Complete testing:

- 1) exercise each & every path in progress from entry to exit.
- 2) exercise every instruction or statement at least once.
- 3) exercise branch & case statement, in each direction.



Control flow graph for below pseudo code

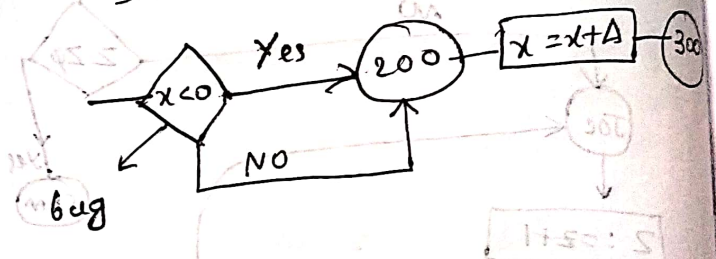
```

If (x < 0) goto 200
x = x + A
200 : x = x + A
300 : continue
  
```

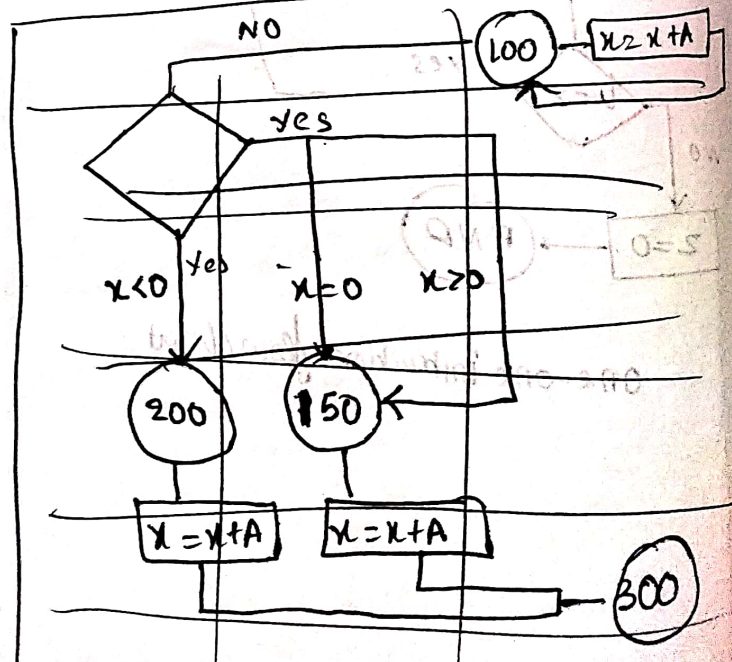
Path 1 (No) = $x + 2A$
 Path 2 (Yes) = $x + A$

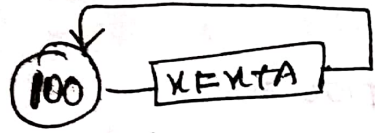
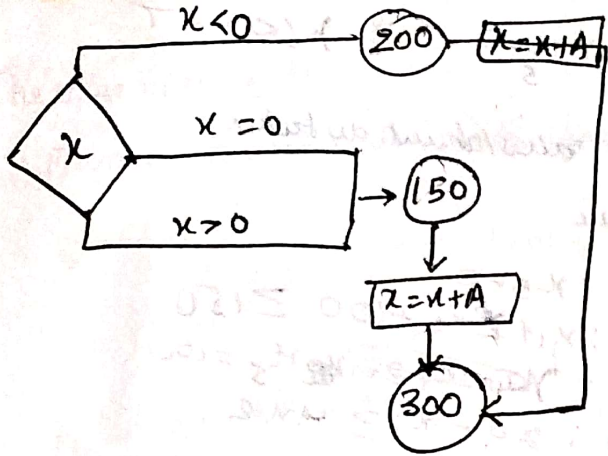
* hidden bug occur when condition leads to the same statement in both cases (True) then the bug occur
 And these types of bugs are not identified by Path testing

eg:
 If (x < 0) goto 200
 200 : x = x + A
 300 : continue



eg:
 If (x), 200, 150, 150
 100 : x = x + A goto 100
 200 : x = x + A
 150 : x = x + A
 300 : continue

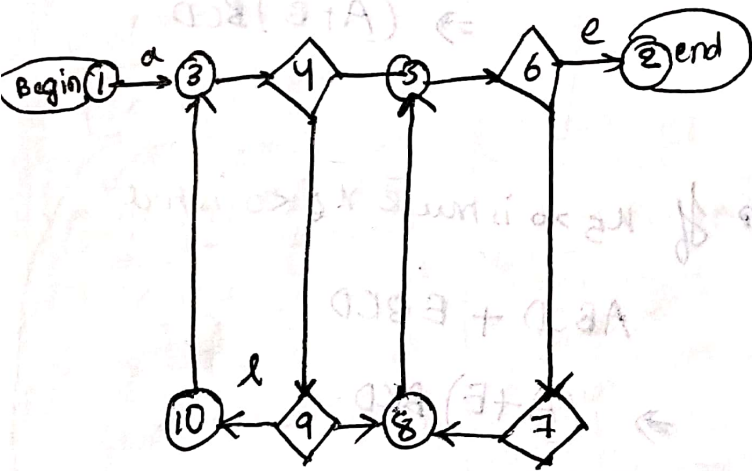




↓
It does not stabilize 2nd statement
& it is an infinite loop bug.

Path testing criteria :-

- (1) Path testing / path coverage (P2)
- (2) Segment testing (P1) / node testing (C1)
- (3) Branch testing (P2) (C2)



Path predicates :-

- > mapping all input values into array is called input vector.
- > expression that is to be evaluated is called as the predicate
- > If $x=0$ do A_1
else if $x=1$ do A_2
else A_3
 $\therefore A_3$ is dependent on predicate $x=1$
and $x=0$ is the independent predicate.

$$x + y = 90$$

$\therefore x$ & y are co-related variables.

$$y = 2$$

$$\text{If } x + y \geq 7$$

then x & y are co-related variables

$$x = 2$$

$$\text{If } y > 1$$

then x & y are independent predicates

If at least one variable is common in two predicates, then they are called co-related predicates

Predicate Interpretation :-

$$\text{If } x_1 + 7 \geq 0 \quad - \quad T$$

$$\& \text{ If } x_1 + y \geq 25$$

$$x_1 = x + 6 \quad - \quad T$$

Control

> If the result of predicate depends upon two variables, then that is called as two place predicate.

> We also need to identify the variables that depends upon the process of execution (order), which is called process interpretation

"Predicate interpretation is symbolic substitution of operators & values in the predicate"

Predicate expressions

$$x_1 + 2x_2 + 100 \geq 150$$

$$x_3 = 100$$

$$x_4 - x_1 \geq 4x_2$$

Three Independent Statements
(OR)
Three predicates

$x_3 = 100$ is obsolete as it cannot be substituted in any statement further after.

Consider

If $x_5 > 0$ OR If $x_6 < 0$ Then

$$x_1 + 2x_2 + 100 \geq 150$$

$$x_3 = 100$$

$$x_4 - x_1 \geq 4x_2$$

Case 1: $x_5 > 0 - T$ & $x_6 < 0 - T$

all statements are taken

Leave

$$A: x_5 > 0$$

$$B: x_1 + 2x_2 + 100 \geq 150$$

$$C: x_3 = 100$$

$$D: x_4 - x_1 \geq 4x_2$$

$$E: x_6 < 0$$

$$F: x_1 + 2x_2 + 100 \geq 150$$

$$G: x_3 = 100$$

$$H: x_4 - x_1 \geq 4x_2$$

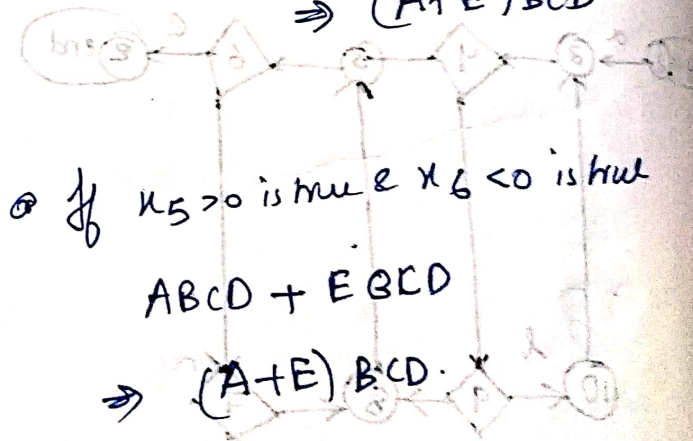
If both cases are false, no execution

If $x_5 > 0$ is false & $x_6 < 0$ is True

$$\bar{A}BCD + EBCD \Rightarrow (\bar{A} + E)BCD$$

If $x_5 > 0$ is True & $x_6 < 0$ is false

$$ABCD + \bar{E}BCD \Rightarrow (A + \bar{E})BCD$$



If $x_5 > 0$ is true & $x_6 < 0$ is true

$$ABCD + EBCD$$

$$\Rightarrow (A + E)BCD$$

Path sensitization

Checking whether the path has entry and exit points

$P_k \rightarrow$ Path coverage

If (Path has loops) 100% Path coverage is not possible
else (simple statements) 100% Path coverage is possible

The entire summary from

Program → flow chart → Control flow graph

↓
Paths identifying

↓
Predicates

P₁ → segment coverage (C₁)

P₂ → Path/link coverage (C₂)

Testing Blindness → Testing done ^{on} commutability
evaluation Testing not identifying bugs

If x=2 goto A, B

A: Do something SAM

B: Do something else SAM

SAM: x is good

If we do not arrive at path exit meaningfully
i.e., even if conditions truth value is
same or different, the control ends at
same place

Testing blindness

① Assignment Blindness

Correct

x = 2

if x > 7

Buggy

x = 2

if x > 7

* In this, the predicate is wrong but may
appear as working. (i.e., above, x=2
assignment in buggy version is unused)

② equality blindness

If one predicate is deciding the value
of another predicate and the
result lands as wrong.

Correct
if A = 3
- if A + B = 6
3 + B = 6

Buggy
if A = 3
if B = 6
3 + B = 6

↓
In here B is not
checked

③ Self Blindness

> If the predicate itself is causing the
problems.

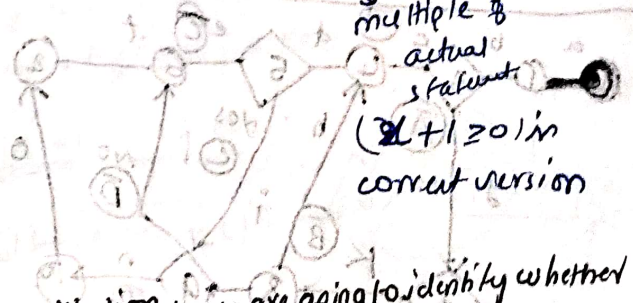
Correct
x = A
if x + 1 > 0

Buggy
x = A
if x + A + 2 > 0

Buggy predicate is the multiple of
the ~~constant~~ constant one

then
A + A + 2 > 0
2A + 2 > 0
2(A + 1) > 0

↓
multiple of
actual
statement
(x + 1 > 0) in
correct version



Path sensitization: We are going to identify whether
the particular path is correct or not.
Heuristic
Path sensitization
Predicate for the
Path sensitization

- ① have a path (already)
- ② we identify path coverage t₁ + t₂
- ③ we can generate control flow graph & identify different paths

- ① Predicate defines the path
- ② And the path contains independent & unco-related predicates and that needs to be covered.

④ we will be identifying the predicates present in the particular path.

⑤ using the predicates, (if more than one predicate present in the control flow graph) and we can form the compound predicates expression & we simplify that expression.

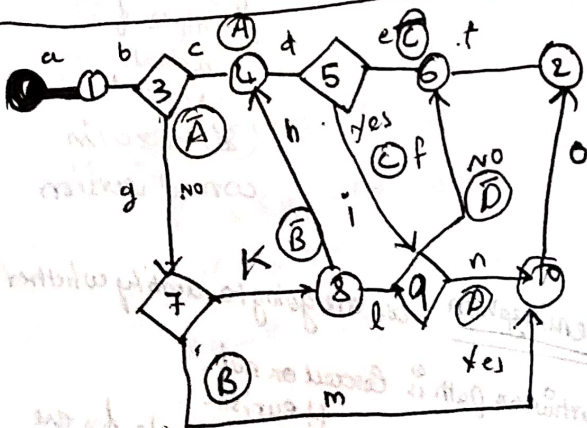
⑥ we need to document every input journey case (ex: A in (A+D)) and formal it away which is the input vector and then that path is called as the achievable path. if we can identify input for all predicates

- ③ Case i: Independent predicates
Case ii: Co-related predicates
Case iii: both

based on the path we may choose one of the iii, Case and if we don't get achievable path, then we will choose another path using ③ ways

- ① Independent & Co-related
 ② Co-related & Independent
 ③ uncorrelated & dependent
 ④ Co-related & dependent

If we consider 4 case, more test cases will be generated relatively



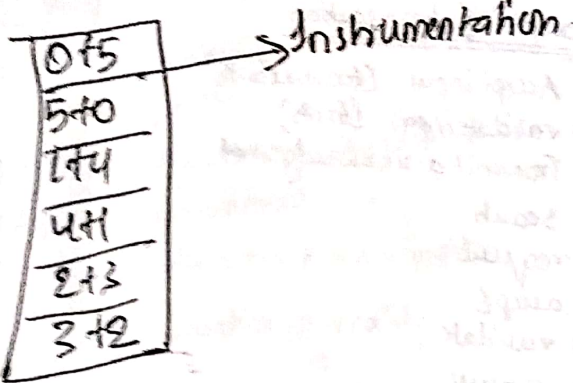
Path name	Predicates
abc def	A \bar{C}
abgkln o	\bar{A} B D
abcd fno	A C D
abcd ffo	A C \bar{D}

8 combinations

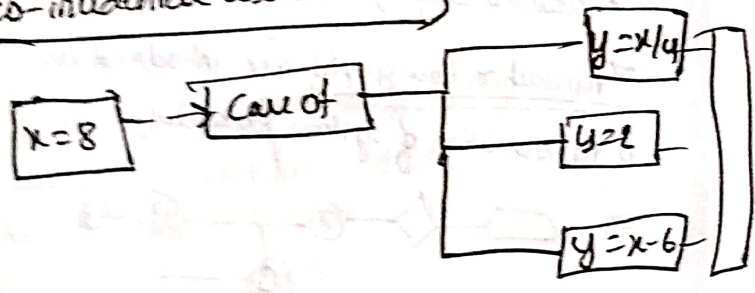
Path instrumentation:

Achieving the outcome in path by using different values is called path instrumentation

$a+b = 5$



Co-incidental correctness



- > This is not a correct (valid method) for testing
- > different expressions → same output
- > But we don't know which will give the output

There are 3 different types

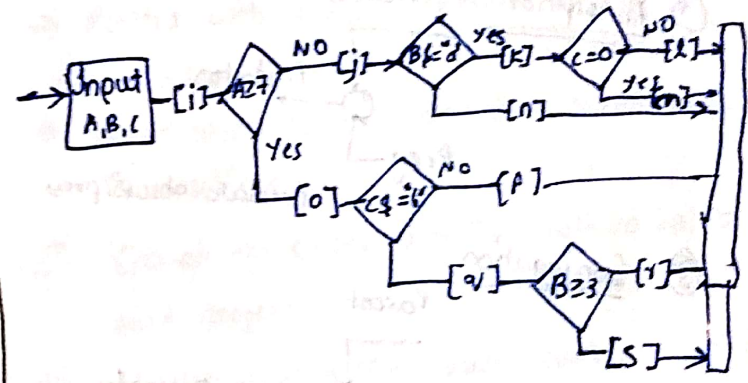
- 1) Interpreter tracer program,
- 2) link marker,
- 3) link count.

To have the bug naming of each & every link (edges) in diagram

Path Instrumentation techniques

- 1) Tracer program (not suggested)
- 2) Link marker
- 3) Link marker counter

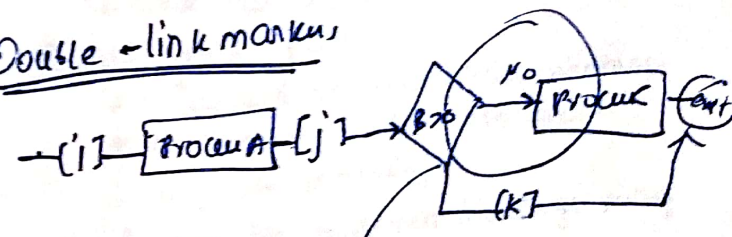
as for each line the machine generates a comment line (Metric)



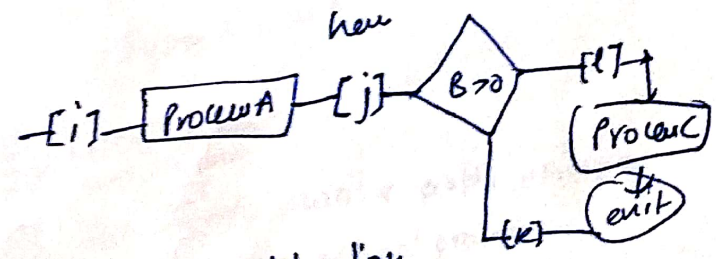
ijk1 - - -
but ij^n, ij^p are shortest paths

> Bugs can easily affect in single link markers by 3rd party.

Double-link markers



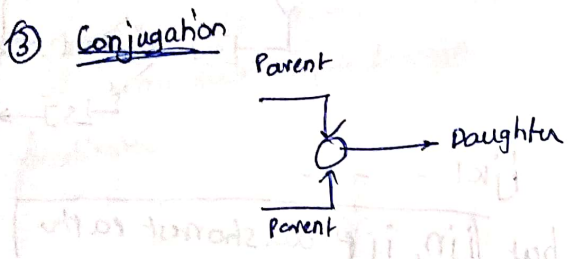
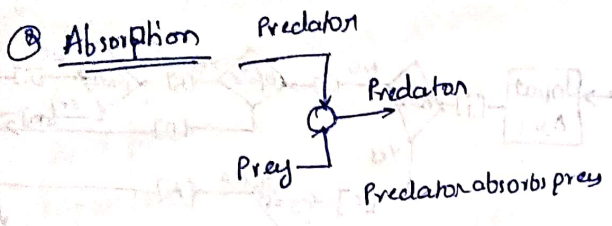
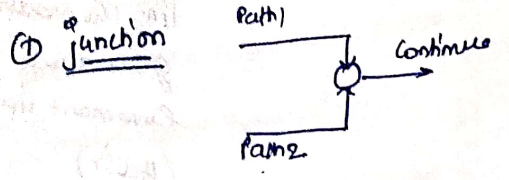
here no marker is placed here we can add a line here



we need to add a link before and after (loop) decision whenever missing

Assignment: Applications of Path taking

Interpretation of mergers (Junctions)



Transaction "A unit of work seen from a system user's point of view"

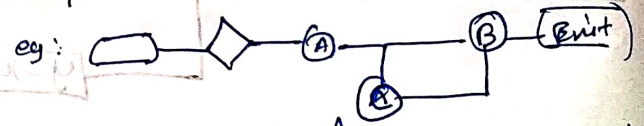
- A transaction begins with birth as a result of some external act.
- A transaction may consist of sequence of operations.

Examples of a transaction

- Accept input (tenative birth)
- validate input (birth)
- Transmit acknowledgment
- Search
- request
- accept
- validate
- process
- update
- cleanup (death)

250
070
170
440
213
912

Transaction flow graphs: are introduced as a representation of systems procedures

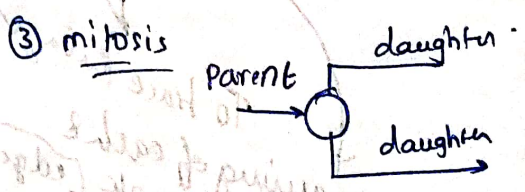
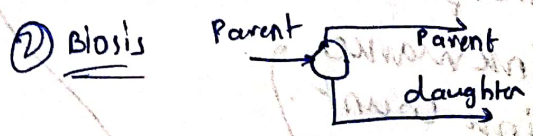
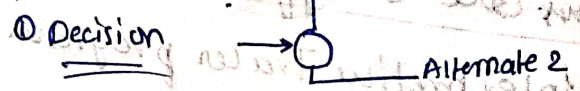


usage: Transaction flow graphs are used for specifying requirements of complicated systems

- loops are infrequent in here
- The most common loop you see is a retry after an error

Interpretations of decision symbol (births)

There are 3



Transaction flow structure UNIT-II

* Imagine we are making transaction flow graph for the process (methodology), but not the code because they may be unstructuredness

Reasons for unstructuredness :-

- ① Process involves human users
- ② Part of flow from external systems
- ③ errors, failures, malfunctions & recovery actions
- ④ Transaction count, complexity and customer environment
- ⑤ new transactions & modifications
- ⑥ Approximation to reality
 - attempt to structure

> Developing a transaction flow graph without the usage of mitosis, binary, absorption and conjugation makes it simple, which is equivalent to the control flow graph

> The above reasons are reasons for bad structures of the making of transaction flow graph.

Transaction flow testing - steps

- First build to obtain transaction flows
 - > represent explicitly (for user convenience)
 - > design details in the main Tr-flows (documentation of TRFs)
 - > Create from PDL (Program description language)
 - > HIPO charts & petri net representations

• Then trace the Transaction.

Transaction flow testing Techniques

- (I) Get the transaction flows
 - from documentation

(II) Inspections, reviews and walkthroughs

⇒ Start from the preliminary design

①. Conducting walkthroughs

- discuss enough transaction types (98% Transactions)
- user needs & functional terms (design independent)
- Traceability to requirements

② Design test for C1 + C2 Coverage

③ Additional Coverage (> C1 + C2)

⇒ Paths with loops, extreme values, domain boundaries.

⇒ weird cases, long & potentially troublesome transactions

④ Design test cases for Transaction splits and mergers.

⑤ Publish selected Test paths early

⑥ Buyer's Acceptance - functional & acceptance tests

(II) Path selection

① covering set (C1 + C2) of functionality

Sensible Transactions

② Add difficult paths

- review with designers & implementors
- exposure of interface problems & duplicated processing
- very few implementation bugs may remain.

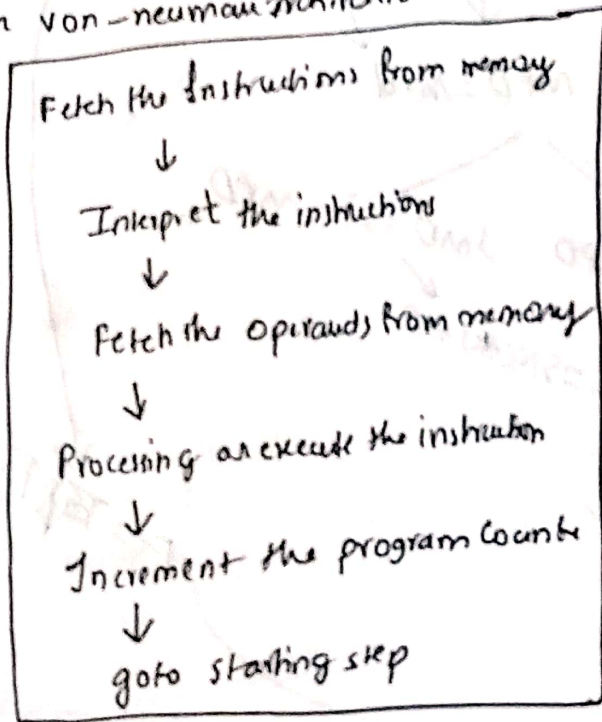
Transaction flow path coverage set belongs in System feature tests

(III) Sensitization

- ① functionally sensitive paths - simple error, exception, external protocol
- ② interface paths - difficult

Data-Flow testing

- we use control flow graph.
- In this testing, we are going to take the different data objects and its sequential execution.
- Based on Architecture there are two data flow machines
 - von-neuman Architecture
 - MIMD (Multi-Instruction-Multiple data Objects)
- > In von-neuman sequential execution of instructions take place
- > In von-neuman Architecture the Program & data stays in same memory
- > In von-neuman architecture



→ In MIMD, we can execute various instructions fast and many at a time (also depends on the compiler)

Data flow graph

- The flow of an data object in different instruction level & data functions is called data flow
- In data flow, it contains nodes & directed edges
- Data flow graph consists of nodes & directed links

for given L, t and d (Z) & Hc

~~cos L~~

PAR DO: $CSL = \cos L$, $SNT = \sin t$
 $CTL = \cos L$, $CST = \cos t$
 $SNL = \sin L$, $TNT = \tan t$

END PAR:

PAR DO: $CSC = CSL * SNT$
 $TNM = CTL * CST$
 $TZF = -SNL * TNT$

END PAR:

PAR DO: $C = \cos^{-1} CSC$
 $M = \tan^{-1} TNM$
 $ZPF = \tan^{-1} TZF$

END PAR:

PAR DO:
 $MPD = M + d$
 $SNC = \sin C$

END PAR PAR DO: $TMD = \tan MPD$
 $SMP = \sin MPD$

PAR DO: $TNF = CSC * TMD$
 $SHC = SNC * SMP$

END PAR:

PAR DO: $Hc = \sin^{-1} SHC$
 $F = \tan^{-1} TNF$

END PAR

$Z = ZPF - F$

$CSL = \cos L$ $CTL = \cos L$ $SNL = \sin L$

$CSC = CSL * SNT$

$C = \cos^{-1} CSC$

$SNC = \sin C$

$TSC = CSC * TMD$

$R = \tan^{-1} TNE$

$HC = \sin^{-1} SNC$

d

$SNT = \sin T$ $CST = \cos T$

$TNM = CTL * CST$

$TZR = SNL * TNY$

$M = \tan^{-1} TNM$

$ZPP = \tan^{-1} TZR$

$MPD = M + d$

$TMD = \tan MPD$

$SMD = \sin MPD$

$SNC = CST * SMD$

$F = \frac{SNC}{SMD}$

Data object state & usage

data objects can be

① defined \boxed{d}

② defined (or) undefined \boxed{ud}

③ usage \boxed{u}

④ in calculations

⑤ used in a predicate

implicit object
→ subject defined explicitly
→ something pushed to stack
→ disappeared
→ returned variable

→ object not used
→ stack is properly
→ return from stack
→ A = 12
→ A = 22

Dataflow Anomaly

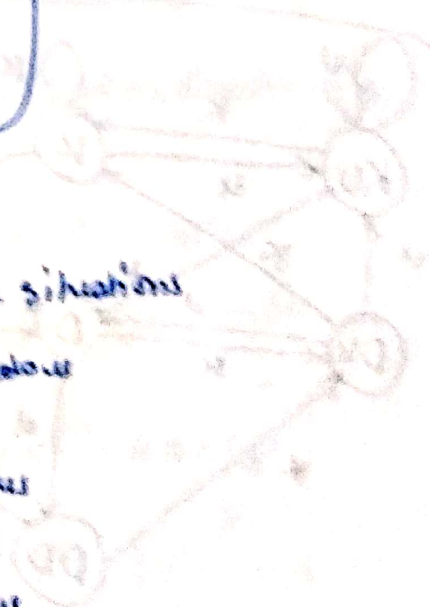
↳ An Anomaly is denoted by a two character sequence of actions
↳ is dependent on application

→ nine possible combinations are possible using d, u, k
Some are bugs, some are suspicious, some are okay

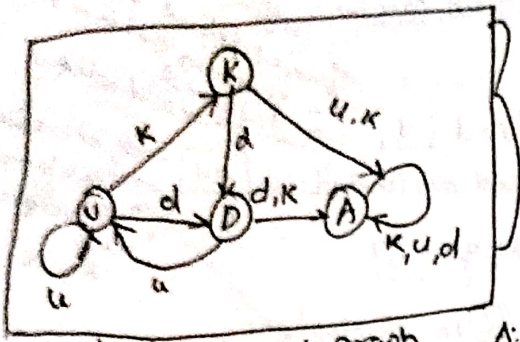
- dd → suspicious
- dk → bug
- du → normal
- kd → normal
- kk → bug
- ku → bug
- ud → suspicious
- uk → normal
- uu → normal

→ 8 letter situations, six situations

- k → possibly anomalous
- d → okay
- u → possibly anomalous
- k → not anomalous
- d → possibly anomalous
- u → not anomalous



Forgiving the data flow anomaly graph



3 anomaly states
3 normal states

① data flow anomaly graph
unforgiving data -

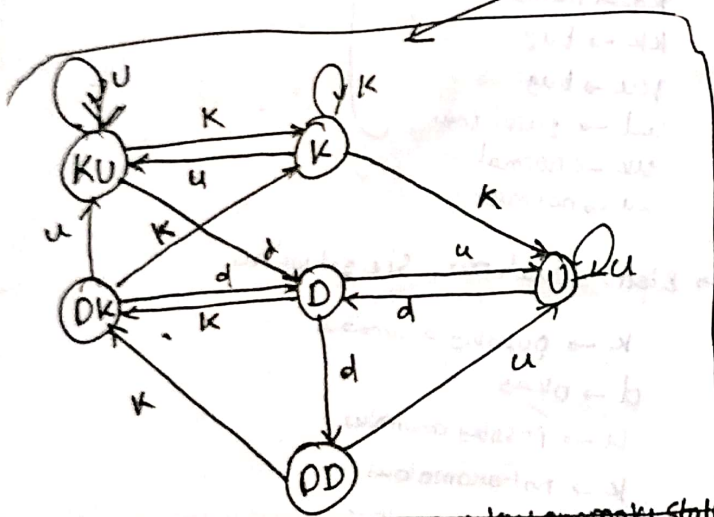
Flow anomaly flow graph
if once an object reaches anomaly state can never return to a normal state

A: Anomalous state
+ once an object reaches the anomalous state, it cannot be used again or cannot be re-used
u: use state
D: define state
K: kill state

Harry developed an improved version of data flow graph

Called forgiving the data flow anomaly graph

where even if the data object reaches to the anomaly state, it ~~cannot~~ can be re-used



② Forgiving data flow graph anomaly

In this the redemption is possible from the anomalous state

Anomaly depends on

- language
- application
- context
- state of programmer's mind

DD, DK, KU: anomaly states

Killing & trying to use data object
data object defined and immediately killed

If data object is defined twice and not used.

Static & dynamic data flow anomalies

- Identifying the syntactic & semantic mistakes comes under static analysis
- Identifying intermediate errors while executing the program comes under the dynamic analysis

> using the static language processor, can identify the syntax errors

> static analysis don't identify all system errors with 100% efficiency because of

(i) dead variables. (killed variable) (unsolvable)

when you kill a variable and try to use it again it leads to anomaly (KU)

If you use a (control) data flow graph which have only one anomaly state, then we are unable to identify dead variables. So based on the code the compiler should select (on) (om) method

(ii) Array (an anomaly as possible)

Array is considered as a single data object
→ If we are going to consider an single element and using static analysis methods, then they cannot identify the position of array element

(iii) Pointers & records (without execution we cannot determine this either)

we cannot ~~use~~ a particular record using static analysis methods. and pointers address also cannot be identified by static analysis methods, but is possible with dynamic analysis methods.

(iv) dynamic sub-routine (or) function names

We cannot identify whether the parameter that are going to be passed to a sub routine are declared or not using static analysis methods

eg:- `inlined(x, y)`

(V) Recovery of Anomalies using alternative OFG

using Forgiving dataflow anomaly graph we can identify certain bugs using static analysis methods whereas in above 4 methods we cannot identify the bugs using static analysis method. But we can use dynamic analysis method.

(vi) Concurrency Interrupt, System Issues

- The external events like interrupts when the control transfers to interrupt handler, we cannot identify bugs using the static analysis method. whereas we can identify the bugs that are internal.

- using static analysis methods, we cannot predict whether the program can execute in a system without any error or not, system issues include memory issues, Processor issues etc

(vii) False Anomaly : not

False anomalies are also identified by static analysis methods

So we mainly use dynamic analysis method. But static analysis methods are worth using

Data flow model :- But demands a huge human testing work

Rules of constructing data flow model :-

- each and every instruction in the program is considered as a node with an unique name. And the entry and exit points cannot be considered as nodes. As every node must have an inlink & outlink.
- we need to write an intention description of how we want to use the predicate above the predicate in model
- combine all the similar nodes into one node.
- And when we combine the nodes, we need to write operations in order



u.k.d

whatsoever write above the link, becomes the weight of the link.

ex:-

START
Input a, b, n

z := 0

if a=1 then z := 1

goto done 1

r1 := 1 c := 1

Power :-

c := c + a

r := r + 1

if r <= n then goto power

z := (c - 1) / (a - 1)

Done 1:

z := i b * z

and.

Data Flow testing

Strategies :-

> data flow model is often referred as structural testing strategy.

1 All definition (clear paths & variables).

2 loop-free segments (path segments) (no loops in path)

• each & every node visited only once.

3 simple path segment

• each node is visited at most twice.

4 All du paths.

defined & used

Dataflow testing strategies

1 All du-paths (ADOP)

2 All uses (AU) strategy

3 All p-uses / some c-uses
all c-uses / some p-uses

(ACU) (SU) (AU) (PU) (CU) (SU)

- ④ All definition strategy (AD)
- ⑤ All p-uses, All c-uses strategy (APU, ACU)

① All Du paths (strongest DFT)

every du path for every variable for every definition to be used

② All uses Strategy

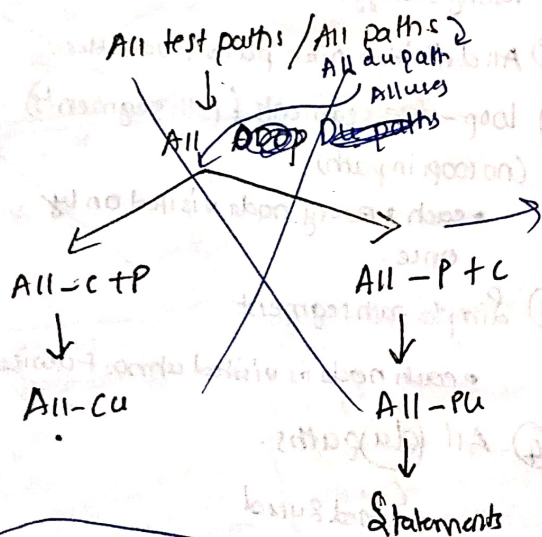
At least one definition - clean path segment from every definition of every variable to every one of that definition under some test

③ $(APU + C) \mid (ACU + P)$

④ Lower every definition by at least one p(c)

⑤

Ordering of DFT strategies / control flow representation



* 90% path coverage can be achieved when we choose the right.

Slicing

① we use static analysis using the slicing we are going to identify the achievable paths

② we eliminate the statements which are invalid

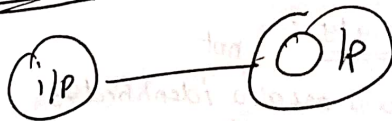
Dicing

① Dicing depends upon the dynamic analysis. In runtime we identify the data object statements. It is also called as dynamic dicing

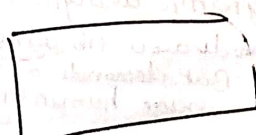
② we are going to get coverage than P2 (APU) coverage < P2

Application, Tool, effectiveness (DFT)

DFT 0



DFT 1 - validation



Comparing Natta (NATP US B) with standard

- 1) Random testing
- 2) Branch testing
- 3) All uses

	No of defect cases conducted	coverage
Random testing	35	93.7
P2	3.8	97.6
APU	11.3	96.7

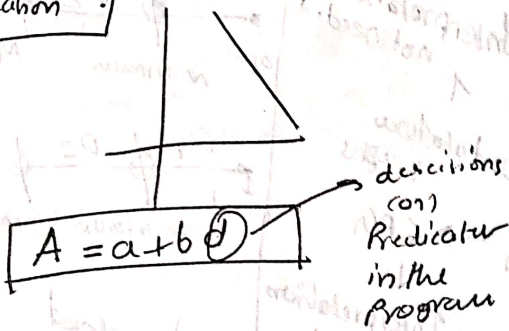
The revised category standard

	NO of test cases	bug found
Random testing	100	79.5
P2	34	85.5
AU	84	90.0

② Another scientist ~~says~~ ^{says} (90% data usage / coverage)

③ ASSET testing system (Released by Caseyaker)

decided by linear regression equation



Almost $(d+1)$ test cases can be used out of $APU, AU, ADPU, ACU$

$ADUP > AU > APU > ACU > \text{scited } APU$

↓
Bug detection rate

④ Shimeall & Leuvor

$$ADUP \sim \frac{1}{2} APU$$

$$APU \sim AC$$

Tools

No tools are present to conduct DFT automatically

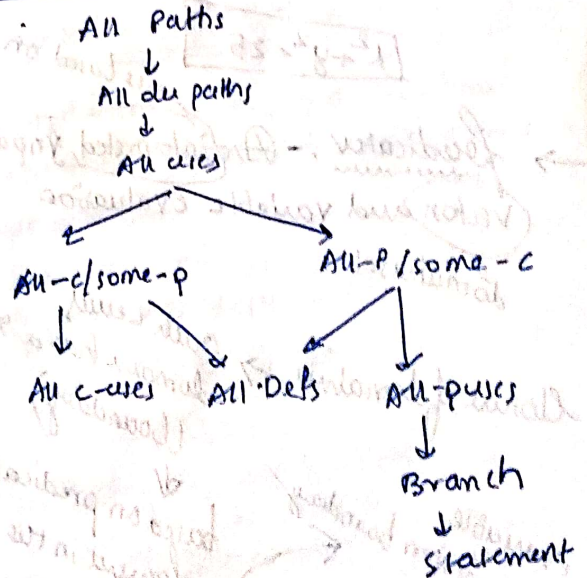
a new compiler is integrated with DFT strategies

efficiency (AU, P1 & P2)

DFT

Test design is same because in path testing & DFT we use control flow graph.

$$\text{Coverage (DFT)} = \text{Coverage (P2)}$$



Relative strength of structural test strategies

⇒ Domain testing :

- Another name for the domain testing is the partition testing.
- Partitions can be made out of the inputs by categorizing them.
- we can check also domain boundaries & associated predicates which are used to define them.
- domain testing donot need any specifications of structural implementation / information of program
- An achievable path from routine entry to exit.
- for each case statement we should have atleast one path
- Domain can be considered as a set.
- The mathematical analysis methods of domain testing if it is integrated into compiler, we require less test cases.

$$x^2 + y^2 < 25$$

→ Predicates :- Are interpreted input vector and variable evaluation
↓
domain set

→ Closure of domains → each & every domain has a range (boundary)

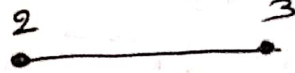
1 variable
↓
1 dimension boundary

n variable
↓
n dimension boundary

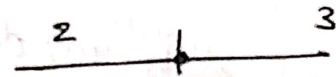
based on predicates present in the program.

→ each & every program have atleast one predicate
→ The boundary of domain can be open or closed

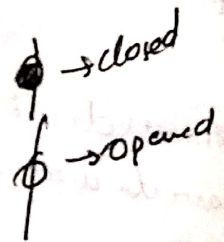
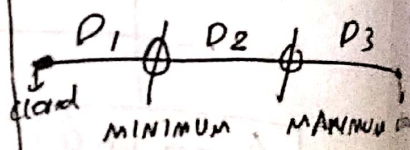
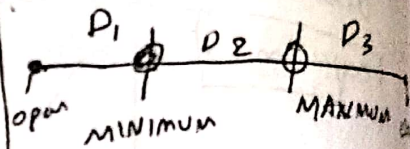
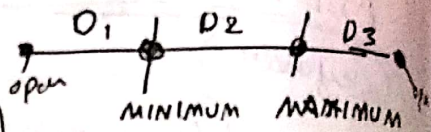
- The boundary point belongs to domain it is closed
(2,3) then 2,3 exist within the (2,3) boundary



- The boundary point belongs to some other domain's open



- Consider a variable x under 3 domains as $x > 0$, $x < 0$ & $x = 0$



Interpretation not needed

→ data flow graphs

→ CFG

↓
Interpretation needed

Bug Assumption :-

- for each testing you assume what bugs may arise from every testing.

① double zero representation

some language support +0 &

~~0~~ - 0
bug

② floating point check for zero

- This bug occurs, when the floating point variable is assigned to '0'.
- even in the routines.
- when subtracted from itself.

③ Contradictory domains : → two domains having two specifications

- If ambiguity is present in the domain then they are contradictory.

④ Ambiguity of domain

- boundary related errors, & the domain is not clearly defined.
- or if you take a combination of two domains then ambiguity of domain arises and if combination is not complete.

⑤ closure semantics

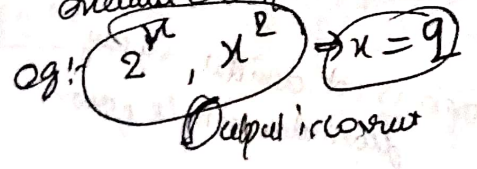
- it is reverse of predicates
- it contains the complements

⑥ Over-specified domain :-

- we cannot make complement of particular variables.
- more constraints, then the domain becomes a null domain
- eg:- byte.

⑦ Faulty logic

- predicate analysis of domain is wrong, even if program executes & output is received



⑧ Boundary related bugs :-

Boundary related bugs

Restrictions in domain testing :-

- we make the input vectors classified into different categories.
- If this classified criteria is not followed by any variable then we cannot conduct domain testing
- restrictions are needed whether to conduct domain testing

① Coincidental Correctness : Domain testing cannot be analysed using domain testing, even though the boundaries of domain are clearly specified

- So our program must be free of this problem

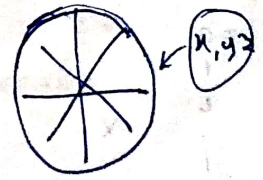
② Representative output/outcome :-

- each and every boundary of domain have at least one predicate (and that predicate can be simple or complex).

- eg: $y > 7$ ✓
 $x > 7$ AND $y < 14$ ✓
 $y > 7$ AND $y < 14$ ✗

The machine decides boundary based on some other detailed expression or connective

like
 If $x=0$ And $y > 7$ or $y < 14$



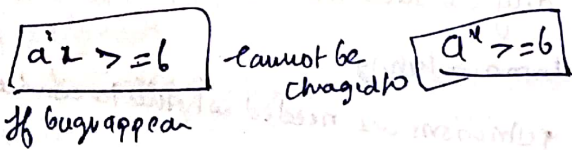
If one part is tested & found valid then it is assumed that all other parts are valid & no further testing is done

③ Simple bound order & Compound Predicate

boundaries seems as simple.
but have complex predicate

④ Functional Homogeneity bug

even though we have bugs, we don't change the originality of the predicate



⑤ Linear vector space

- Research paper published about DT
- There are linear & non-linear ~~predicates~~ equations at predicate level
- In linear equation the Output rate was / successful rate was 99.99%
- For non-linear equations at predicate level, we are going to convert into linear equations without change in originality of the predicate.

⑥ loop-tree-s/w

- Domain testing is hectic & there are loops present
- In the loops, for the same variable in each increment the boundary of domain is changed

$\therefore f_n(i=0; i<=10; i++)$

i=0
1
2
...
10



Therefore we convert looping structure into simpler statements

	Nice domains					ugly domain				
	u_1	u_2	u_3	u_4	u_5					
v_1	D_{11}	D_{12}	D_{13}	D_{14}	D_{15}					
v_2	D_{21}	D_{22}	D_{23}	D_{24}	D_{25}					
v_3	D_{31}	D_{32}	D_{33}	D_{34}	D_{35}					
v_4	D_{41}	D_{42}	D_{43}	D_{44}	D_{45}					
v_5	D_{51}	D_{52}	D_{53}	D_{54}	D_{55}					

Domains are classified into:

① Specified domain

They are ambiguous & contradictory

② Implemented domains: They never become incomplete & inconsistent

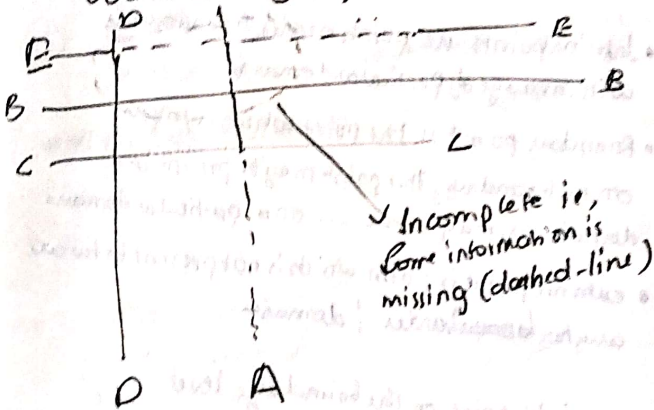
because each & every possible input value is checked against all the domain range

Domain is not decided by any particular single person

eg: u_1, u_2, u_3, u_4, u_5
 u_1, u_2, u_3, u_4, u_5
if two domain have same specification then they are inconsistent if you are not getting the output for a domain

Nice domain properties

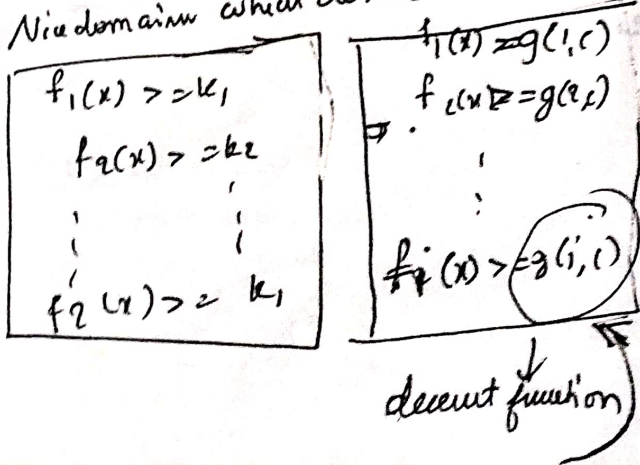
- ① It contains both linear or non-linear boundaries
- ② But nice domains only accept the linear boundaries, if any non-linear boundaries are present then they are converted into linear boundaries
- ③ Nice domains support complete boundaries (i.e., $-\infty$ to $+\infty$)



For complete boundaries you can use only one set of test cases to check all the variables present in the particular boundary level.

- nice domains are complete domain
- by conducting one testing we assume even other path are correct without more testing.

④ Systematic Boundaries are used in Nice domain which describe

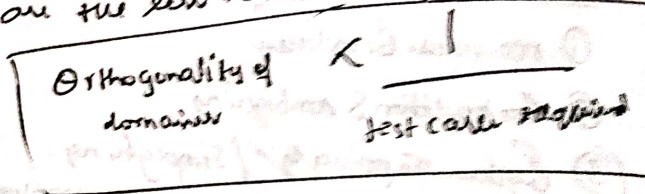


Systematic boundaries are easy to explain

eg: entering value for x
 $\therefore x_1, x_2, x_3, x_4, \dots$
 the x boundary is shared by all other x_1, x_2, x_3, \dots
 in the above function example

⑤ Orthogonal Boundaries

- The primitives can be summed up to construct various sets of structures for which each structure is valid & legal.
- The more orthogonal the domains are the less testing is required



⑥ closure consistency

- clear inputs
 - clear specifications for domain
- Only then we are going to get an achievable path

⑦ Coherence

- Taking two separate entities & making them appear as one entity of a domain due to its convex

Domain bugs in domain testing

⑧ Simply Connected Domain

If the connections between the boundaries are simple irregularities of no. of domains

If all these properties are satisfied, only then we can call it a nice domain, even if a property is not specified correctly then it becomes an ugly domain

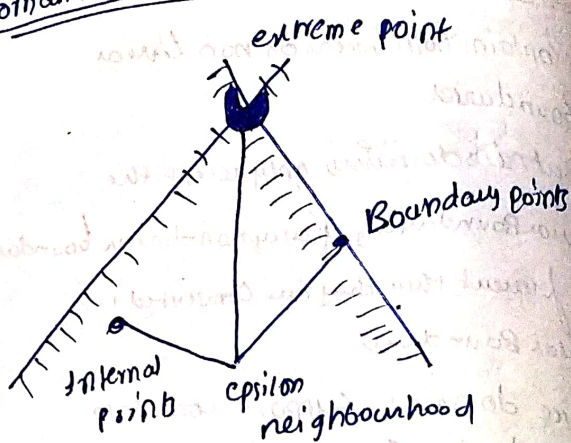
Ugly domain properties

- ① non-linear boundaries
- ② Contradiction & ambiguity
- ③ System topology / Simplifying system topology
- ④ holes filling

Domain testing

every domain is defined by boundaries.

- * test points should be considered near the boundaries / on the boundaries
- * classifying the domain boundaries, and if values are out of the boundaries defined.
- * redundant elimination of boundaries w.r.t domain
- * after conducting testing, we should do a post analysis which shows whether a boundary is faulty (or) not
- * we need to test boundaries for each individual boundary



- Interior points are points nearer to boundary within range of particular domain.
- Boundary point is the point which is taken on the boundary, this point may be present in a domain (or) may not be ... on a particular domain.
- extreme point is point which is not present between any two boundary / domain

on point: point on the boundary level

off point: off point is point on the boundary which is not tested correctly with respect to closed boundary

off point is point on the boundary which is currently being tested with respect to open boundary

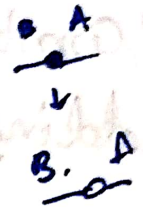
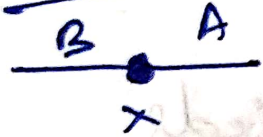
closed off outside open off inside

① closure bugs → ^{Initially $x > 0$} evaluated predicate
 is wrongly evaluated



$x > 0$ is intention
 ↓
 but $x >= 0$

② shifted bugs → moving of the boundary
 Points causes these bugs



③ Tilted Bugs → position of domain
 is slightly changed

④ Missing Bugs → missing boundaries

⑤ extra Bugs → extra boundaries

* All the bugs are present in 1D, 2D, 3D domains.

UNIT - III

Path products and path expression

Path expression is a set of algebraic representations of sets of paths in a graph

"flow graphs are the abstract representation of programs"

most testing & debugging tools use flow graph analysis technique

⇒ motivation

↓
A path expression can be converted into an algebraic expression that can be used to examine structural properties of flow graphs

"normally flow graphs are used to denote only control flow connectivity"

↓
The simplest weight we can give to a link is a name

↓
using link names as weight, we can derive an equivalent algebraic expression

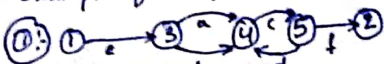
↓
To trace, you traverse a succession of link names

↓
eg: if you traverse abcd, then the name of that path segment is abcd

↓
The path name is also called as a path product

⇒ Path product

examples of some paths



eaef, ebef, ebcd, eacdf, ebcd -- etc



abd, abc, abcbcd -- etc

Path expression

• taking a pair of nodes in a graph & set of paths between the node → set of paths must be represented in uppercase letters

on using $x = ac, abc$ ac tabe denotes 'or'

"Any expression that consists of two successive path segments is conveniently expressed by concatenation or path product"

so any expression that consists of two successive path segments is on denotes a set of paths between two nodes is called a path expression

Path products rule

if $x = abcde$ $y = fg hijk$
then $xy = abcdefghijk$ (if x is followed by y)

Similarly

$ax = aabcde$

$xy = abcdefghijk$

if x represents a set of paths on path expression and y also represent another set of paths on path expression

then product is all combinations of x & y paths combined

eg: $x = abc + def + ghi$

$y = uvw + z$

then $xy = abcuvw + defuvw + ghiuvw + abczt + defz + ghiz$

"if a link segment (or) name repeats, we express no. of repetitions in terms of power"

$a^1 = a, a^2 = aa, a^3 = aaa, a^4 = aaaa \dots a^n = a \dots n$ times

Similarly

$x = abc : x^2 = abcabc : x^3 = abcabcabc$

** "The path product is not commutative" **

$xy \neq yx$

** "The path product is associative" **

$A(BC) = (AB)C = ABC$

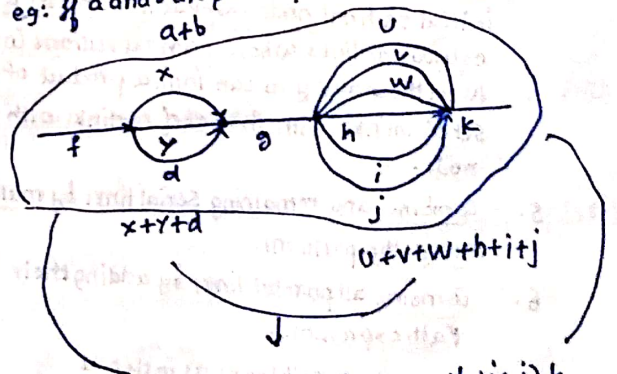
** "The path without any links should also be represented" **

$a^0 = 1$ link
 $x^0 = 1$ path's set **

Path sums rule (dealing with the '+')

"Path sum denotes the paths in parallel between nodes"

eg: if a and b are parallel paths between two nodes



⇒ $f(x+y+d)g(u+v+w+t+i+j)k$

Distributive law :- $A(B+C) = AB+AC$
 $(B+C)D = BD+CD$ } holds good

eg: $e(atb)(ctd)f = eact + eadf + ebct + ebd f$

Absorption rule : $X + X = X$

X denotes a set of paths

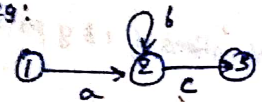
eg: $X = a + aa + tabc + abcd + def$

then $X + a = X$; $X + aa = X$

$X + abc = X$; $X + abcd = X$; $X + def = X$

Loops: "loops are infinite set of parallel paths"

eg:



∴ path expression would be

$X = ab^*c = abc + ac + abbc + abbbc + abbbbc + \dots$

Reduction procedure Algorithm :-

This section presents a reduction procedure for converting the flow graph whose links are labelled with names into a path expression that denotes the set of all entry/exit paths in that flow graph. This procedure is a node by node removal algorithm

Procedure :-

1. Combine all serial links by multiplying their path expression.
2. Combine all parallel links by multiplying adding their path expression.
3. Remove all self loops (from any node to itself) by replacing them with a link of x^* , where x is the path expression of that link in that loop.

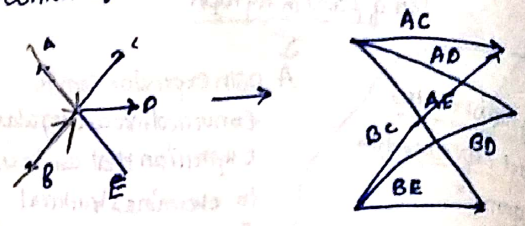
Loop :

4. Select any node for removal other than the initial or final node. Replace it with a set of equivalent links whose path expressions correspond to all the ways you can form a product of the set of inlinks with the set of outlinks with that node.
5. Combine any remaining serial links by multiplying their path expressions.
6. Combine all parallel links by adding their path expressions.
7. Remove all self loops as in step-3
8. Does the graph consist of single link between the entry node and exit node?
If yes then the path expression for that link is path expression for original flow graph

Otherwise return to step 4

end Loop

Note :- "A flow graph can have many equivalent path expressions between a given pair of nodes; that is there are many different ways to generate the set of all paths between two nodes without affecting the content of that set."



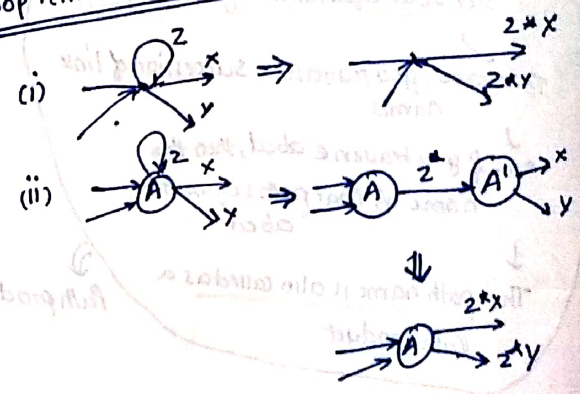
∴ $(a+b)(c+d+e) = ac + ad + ae + bc + bd + be$

The above is the cross term step: the fundamental step of the reduction algorithm

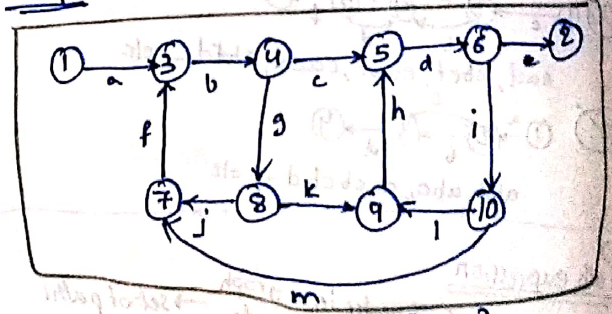
It eliminates one node from total no. of nodes

If this procedure is continued successfully there will be only one entry node and one exit node

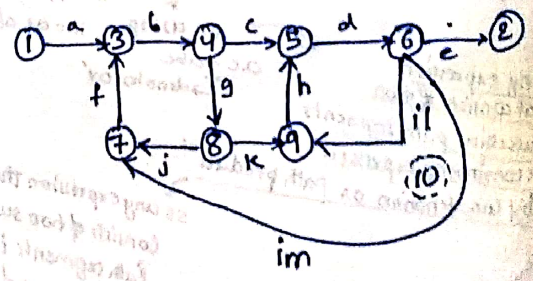
loop removal operations ∴ There are two ways to look at the loop removal operation



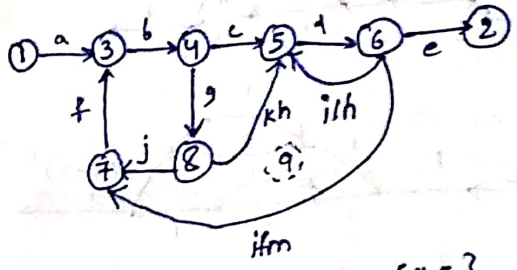
example :-



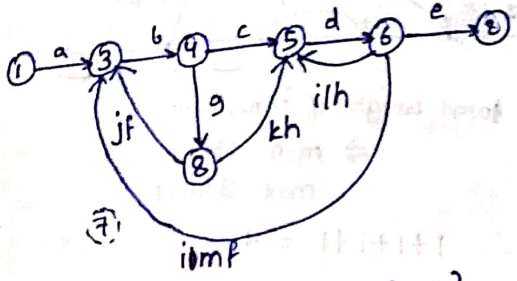
remove node 10 Apply steps 4, 5, 6



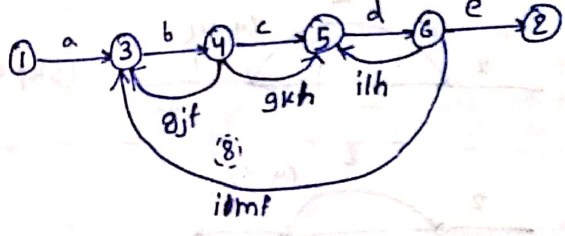
* remove node 4 apply steps {4,5}



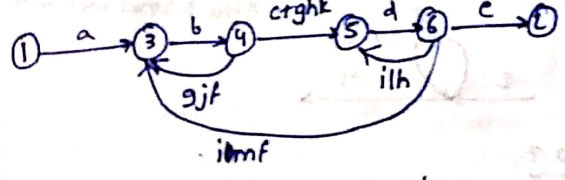
* remove node 7 apply steps {4,5}



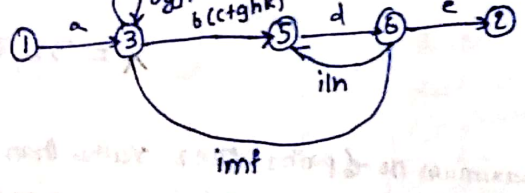
* remove node 8 apply steps {4,5}



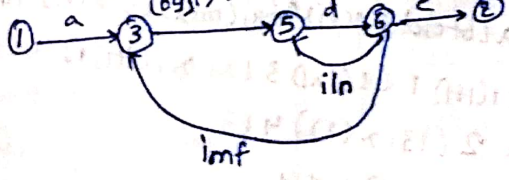
* c & gkh are parallel terms



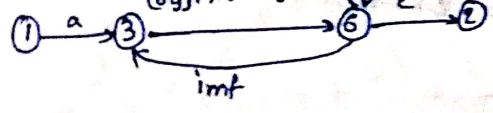
* remove the node u: it gives a loop term



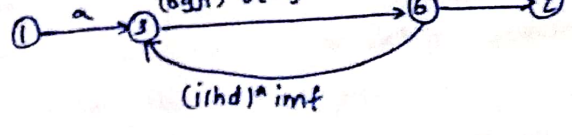
* Apply loop removal



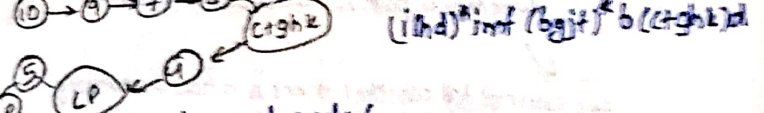
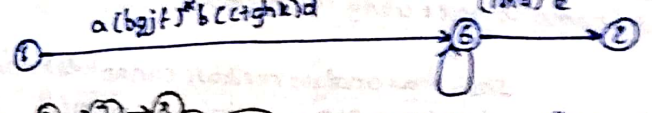
* remove node 5



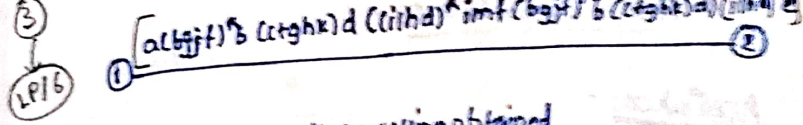
* Apply loop removal



* removing node 3

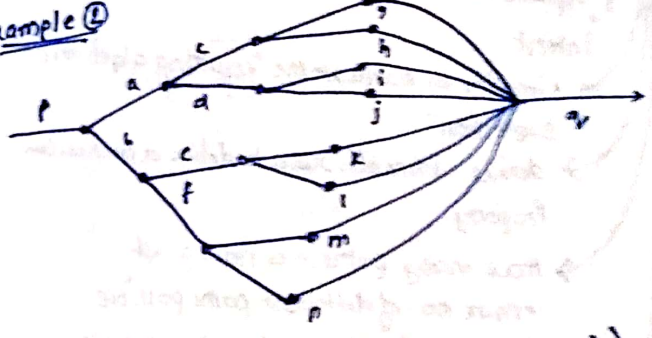


* removing loop and node 6



is the final path expression obtained

example 4



$$\Rightarrow P(a(cctgh) + d(itj)) + b(eck + i) + f(mmm)) Q$$

Regular expressions & flow anomaly detection

Problem "The generic flow-anomaly detection problem is looking for any specific sequence of options considering all possible paths through a routine"

Method "Annotate each link in the graph with appropriate operators on the null operator 1. & 'simplify' " you now have a regular expression that denotes all possible sequence of operators in that graph"

Huangs theorem: let A, B, C be non empty sets of characters sequences whose smallest string is at least one character long. Let T be a two character string. Then if T is a substring of ABC, then T will appear in ABCC

eg:- let A=PP; B=STR; C=VP; T=SS
According to the theorem ss will appear in PP(STR)VP

$$\begin{aligned} \therefore A &= P + PP + PS \\ B &= PSY + PS(Y+PS) \\ C &= VP \\ T &= PY \end{aligned}$$

$\therefore (P + PP + PS)(PSY + PS(Y+PS))VP$
There is no sequence in $ABCC$ of PY

Limitations :- Alongs theorem, beyond three characters it becomes complex using this method

↓
 static flow analysis methods cannot determine whether a path is achievable or not.

↓
 we cannot tell whether there is a flow anomaly and where, but we can tell whether the path is achievable or not.

Applications :-

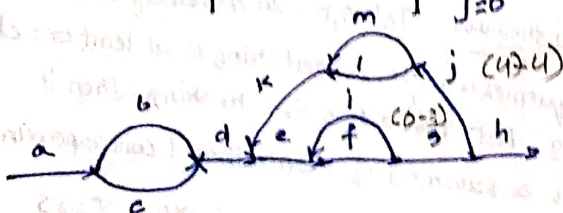
- convert program (graph into a path expression)
- replace link names with link weights for our interest
- simplify or evaluate the "resulting algebraic expression"
- derive arithmetic rules to define a particular property.
- How many paths in a flow graph
 - max no. of different paths possible
 - what is least no. of paths possible
 - How many different no. of paths are there
 - average no. of paths. (meaningless at source)

Maximum Path Count Arithmetic

• There are three cases: parallel links, serial links, loops

case	Path expression	weight expression
Parallel	A+B	$W_A + W_B$
Series	AB	$W_A W_B$
Loop	A^n	$\sum_{j=0}^n W_A^j$

eg:-



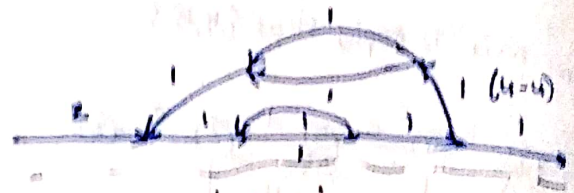
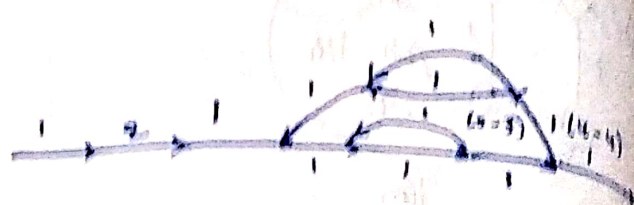
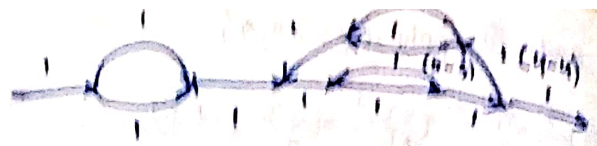
Path expression:-

$a(btc)d \sum e(fg)^n h$

step 1: replace link name with maximum of paths of that link (i)

step 2: combine parallel loop pairs outside the loop

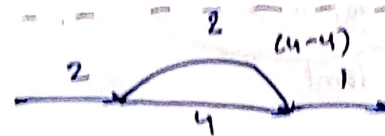
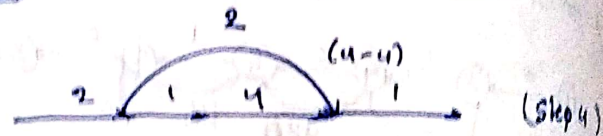
step 3: remove the nodes



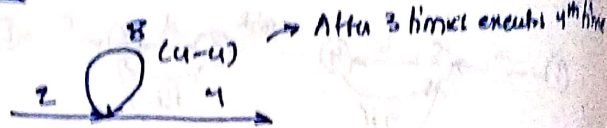
step 4: total weight of inner loop
 ⇒ min: 0 times
 max: 3 times

$\therefore 1+1+1+1 = 4$

step 5: multiply link weights $1 \times 4 = 4$



step 6: multiply weight of link $2 \times 4 = 8$



step 7:

$\therefore 2 \rightarrow 8^4 \times 4 = 32,768$

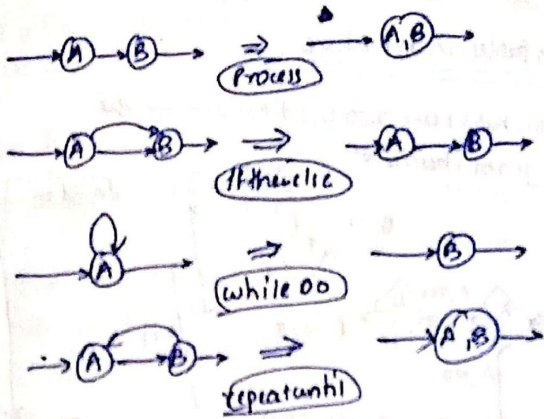
∴ maximum no. of paths 32768 rather than 32,768 as 4th time will be taken on 4th time

$a(btc)d \sum e(fg)^n h$
 $= 1(1+1) 1 (1(1 \times 2) 3 \times 1 \times 1 (1+1) 1) 4(1 \times 1) 3$
 $= 2(13) \times (2) 4 \times 4$
 $= 2(4 \times 2) 4 \times 4$
 $= 2 \times 8 \times 4 = 32,768$

Structured flowgraph

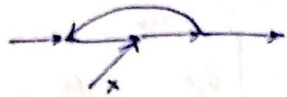
: the flowgraphs that do not involve ad-hoc rules such as not using goto's

"A structured flowgraph is one that can be reduced to a single link by successive applications of transformations."



unstructured subgraphs

1. Jumping into loops



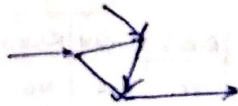
Intention of the Program is decided when reduction procedure is applied

2. Jumping out of loop



Statements that are outside of the loop are reached

3. Branching into decisions



Intention of statements is changed

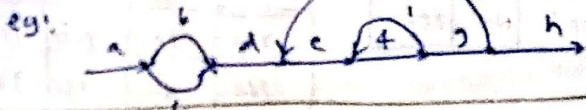
4. Branching out of decisions



Intention of condition & statements is changed

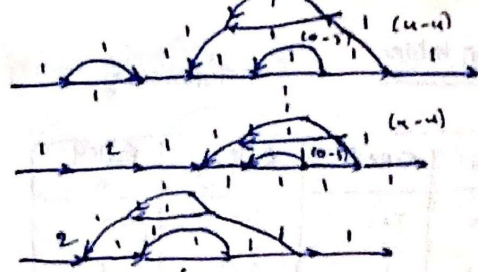
Lower path count arithmetic (lower bound on n. of paths)

Case	Path expression	Weight expression
Parallel	$A+B$	$w_A + w_B$
Series	AB	$\max(w_A, w_B)$
Loop	A^n	$1, w_A$



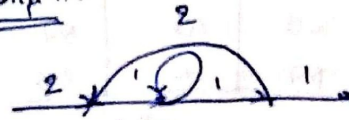
mean processing time of a routine

$(TA + TB) / (PA + PB) = T + B$; $PA + B = PA + PB \rightarrow$ Parallel
 $TAB = TA + TB$; $PAB = PA + PB \rightarrow$ series
 $TA = TA + TLPL / (1 - PL)$; $PA = PA / (1 - PL) \rightarrow$ loop

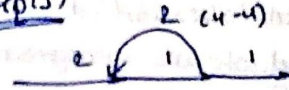


From step (4) same as previous different than previous

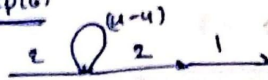
step (4):



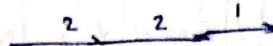
step (5):



step (6):



step (7):



step 8



∴ At least 2 path to cover

Logic Based testing:

- functional requirements of many programs are specified by decision tables.
- consistency and completeness can be analysed by boolean algebra. Boolean algebra is trivialized by K-v charts.
- Boolean algebra (sentential calculus) is most basic of all logic systems.
- Higher order logic systems are used for formal specifications.

Knowledge based system :- (artificial intelligence system)

- knowledge based system has become the programming construct of choice for many applications.
- Knowledge based system incorporate knowledge from a knowledge domain such as medicine, law, engineering into a database. Then the data is queried and the solutions are extracted.
- Decision tables are extensively used in business data processing.
- Decision tables are preprocessors as extensions to COBOL are in common use.
- Boolean algebra is embedded in the implementation of these processors.

examples of decision tables

Condition entry

eg: 1

	Rule 1	Rule 2	Rule 3	Rule 4
Condition 1	yes	yes	NO	NO
Condition 2	yes	I	NO	I
Condition 3	NO	yes	NO	NO
Condition 4	NO	yes	NO	yes
Action 1	yes	yes	NO	NO
Action 2	NO	NO	yes	NO
Action 3	NO	NO	NO	yes

- "A rule specifies whether a condition should or should not meet for the rule to be satisfied".
- Condition and predicate are synonymous.

eg: 2 : Printer Troubleshooting

		Rules							
Conditions	Printer not plugged	Y	Y	Y	Y	N	N	N	N
	Printer does not print	Y	Y	N	N	Y	Y	N	N
	A red light is flashing	Y	N	Y	N	Y	N	Y	N
	Printer is unrecognized	Y	Y	N	Y	N	N	Y	N
Actions	check the power cable			X					
	check the computer cable	X	X						
	check printer software	X	X		X	X			
	check/replace ink	X	X		X	X			
	check for paper jam	X	X						

"In addition to the stated rules a default rule must also be provided"

Decision table processors :-

- decision tables can be automatically translated into code and such are a higher-order language

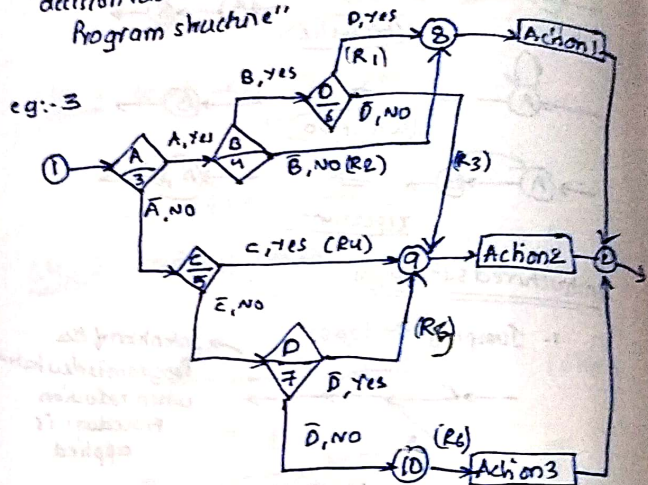
Decision tables as a basis for test case design

- 1. specifications are given as decision tables or can be converted into one

2. The order in which the predicates are evaluated does not affect the interpretation of the rules.
3. The order in which rules are evaluated will not affect the resulting action.
4. once a rule is satisfied and action is selected, no other rule needs to be evaluated.

Decision tables and structure

"decision tables are also used to examine the program structure"



"If the decision appears on a path put a Yes or no as appropriate. If the decision does not appear on the path put a I"

	Rule 1	Rule 2	Rule 3	Rule 4	Rule 5	Rule 6
Condition A	yes	yes	yes	NO	NO	NO
Condition B	yes	NO	yes	I	I	I
Condition C	I	I	I	yes	NO	NO
Condition D	yes	I	NO	I	yes	NO
Action 1	yes	yes	NO	NO	NO	NO
Action 2	NO	NO	yes	yes	yes	NO
Action 3	NO	NO	NO	NO	NO	yes

for above sample program this is the decision table (3)

Expanding the immaterial cases

eg: 4

	Rule 1	Rule 2
Condition 1	yes	yes
Condition 2	I	NO
Condition 3	yes	I
Condition 4	NO	NO
Action 1	yes	NO
Action 2	NO	yes

⇒

Rule 1-1	Rule 1-2	Rule 1-3	Rule 1-4
yes	yes	yes	yes
yes	NO	NO	NO
yes	yes	yes	NO
NO	NO	NO	NO
yes	yes	NO	NO
NO	NO	yes	NO

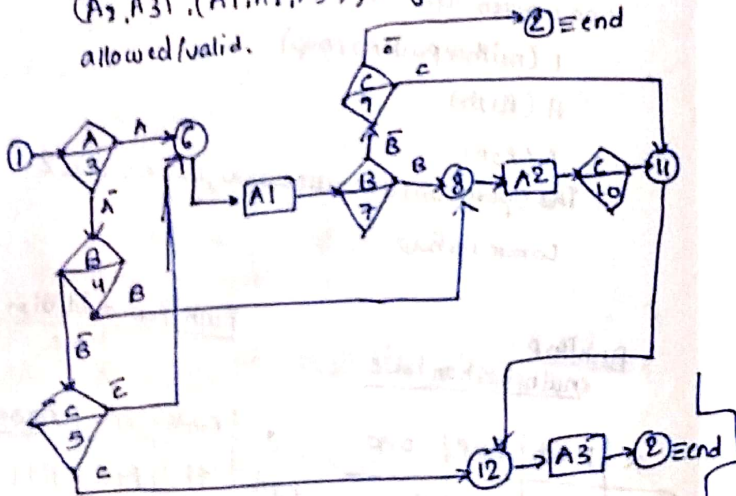
similarity for eg-3

	Rule 1	Rule 2	Rule 3	Rule 4	Rule 5	Rule 6
Condition A	YY	YYY	YY	NNNN	NN	NN
Condition B	YY	NNNN	YY	YYNN	NY	YN
Condition C	YN	NNYY	YN	YYYY	NN	NN
Condition D	YY	YNNY	NN	NYYN	YY	NN

"As a first check count numbers of Y & N in each row, we can identify bug that way"

eg: 5: A trouble some program

- If condition A is met, do process A1 leaving about other actions are performed on other conditions are met or not.
- If condition B is met, do process A2, no matter other conditions are met or not.
- If condition C is met do process A3 no matter other conditions are met or not.
- If above 3 conditions are not met then do processes A1, A2, A3
- valid processes are (A1), (A2), (A3), (A1, A2), (A2, A3), (A1, A2, A3); any other order is not allowed/valid.



"In the B & C cases A2 & A3 processes would be bypassed"

	$\bar{A}\bar{B}\bar{C}$	$\bar{A}\bar{B}C$	$\bar{A}B\bar{C}$	$\bar{A}BC$	$A\bar{B}\bar{C}$	$A\bar{B}C$	$AB\bar{C}$	ABC
Condition A	N	N	N	N	Y	Y	Y	Y
Condition B	N	N	Y	Y	Y	Y	N	N
Condition C	N	Y	Y	Y	N	N	Y	N
Action 1	Y	N	N	N	Y	Y	N	N
Action 2	Y	N	Y	Y	N	N	Y	N
Action 3	Y	Y	Y	Y	N	N	Y	N

Path expressions

"In logic based testing, we focus on the truth values of control flow predicates"

↳ A predicate is implemented as a process whose outcome is a truth functional value

Boolean Algebra

Steps:

1. Label each decision with an uppercase letter that represents the truth value of the predicate. The Yes or True branch is labelled with a letter say A and the No or False branch with some letter overscored
2. The truth value of a path is the product of individual labels. Concatenation or products mean 'AND'.
3. If two or more paths merge at a node, the fact is expressed by a use of + sign which means OR.

eg: for the eg: 5

(N → node)

$$N6 = A + \bar{A}\bar{B}\bar{C}$$

$$N8 = (N6)B + \bar{A}\bar{B} = AB + \bar{A}\bar{B}\bar{C}B + \bar{A}\bar{B}$$

$$N11 = (N8)C + (N6)\bar{C}$$

$$N12 = N11 + \bar{A}\bar{B}\bar{C}$$

$$N2 = N12 + (N8)\bar{C} + (N6)\bar{C}$$

Rules of Boolean algebra :-

• AND (X), OR (+), NOT (\bar{X})

1. $A + A = A$
2. $A + 1 = 1$
3. $A + 0 = A$
4. $A + B = B + A$ // commutative
5. $A + \bar{A} = 1$
6. $AA = A$
7. $A \times 1 = A$
8. $A \times 0 = 0$
9. $AB = BA$
10. $A\bar{A} = 0$
11. $A = A$
12. $\bar{\bar{A}} = A$
13. $\bar{1} = 0$
14. $\overline{A+B} = \bar{A}\bar{B}$ // demorgens law
15. $\overline{AB} = \bar{A} + \bar{B}$
16. $A(B+C) = AB + AC$ // distributive
17. $(AB)C = A(BC)$ // associative
18. $(A+B)+C = A+(B+C)$ // additive
19. $A + \bar{A}B = A + B$ // absorption
20. $A + AB = A$

Points to ponder

- Individual letters in Boolean Algebra are called Literals.
- The product of several literals is called a product term.
- An Arbitrary boolean expression that has been multiplied out so that it consists of sum of products $(ABC + DEF + GH)$ is said to be in sum of products.
- The resultant of simplifications is again the form of sum of products and each product term in such a simplified version is called prime implicant.

$\therefore N_6 = A + \bar{A}\bar{B}\bar{C} = A + \bar{B}\bar{C}$

$N_8 = (N_6)B + \bar{A}\bar{B}$
 $= (A + \bar{B}\bar{C})B + \bar{A}\bar{B}$
 $= AB + \bar{B}\bar{C}B + \bar{A}\bar{B}$
 $= AB + 0 + \bar{A}\bar{B}$
 $= AB + \bar{A}\bar{B}$
 $= (A + \bar{A})B$
 $= B$

shouldn't be $B + \bar{A}\bar{C}$ But B

$N_{11} = (N_8)C + (N_6)\bar{B}\bar{C}$
 $= BC + (A + \bar{B}\bar{C})\bar{B}\bar{C}$
 $= BC + A\bar{B}\bar{C}$
 $= C(B + \bar{B}A)$
 $= C(B + A)$
 $= AC + BC$

$N_{12} = N_{11} + \bar{A}\bar{B}\bar{C}$
 $= AC + BC + \bar{A}\bar{B}\bar{C}$
 $= AC + BC + \bar{A}\bar{B}\bar{C}$
 $= C(B + \bar{A}\bar{B}) + AC$
 $= C(\bar{A} + B) + AC$
 $= C\bar{A} + AC + BC$
 $= C + BC$
 $= C$

$N_2 = N_{12} + (N_8)\bar{C} + (N_6)\bar{B}\bar{C}$
 $= C + BC + (A + \bar{B}\bar{C})\bar{B}\bar{C}$
 $= C + BC + \bar{B}\bar{C}$
 $= C + \bar{C}(B + \bar{B})$
 $= C + \bar{C}$
 $= 1$

loops complicate things

similar $N_{12} \neq C + \bar{A}\bar{B}\bar{C}$ But just C

- Implicants are the product terms with special properties that we are trying to implement i.e., An implicant P of a function F is a product term 'P' such that $F = 1$ whenever $P = 1$.
- A prime implicant P of F is any implicant that is not covered by any other implicant of F.
- An essential prime implicant of function F is one that covers a minterm of F not covered by any other prime implicant of F.

Push/Pop arithmetic

: useful in debugging and test cases design

Case	Path expression	Weight expression
Parallel	$A + B$	$W_A + W_B$
Series	AB	$W_A W_B$
Loop	A^k	W_A^k

: on a given link notations

- 1 (neither push nor pop)
- H (Push)
- P (Pop)

: The operations are associative, distributive & commutative

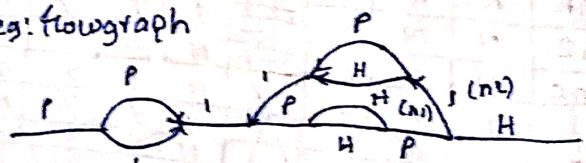
Push/Pop multiplication table

x	Push	Pop	None
Push	H^2	1	H
Pop	1	P^2	P
None	H	P	1

Push/Pop addition table

.	Push	Pop	None
Push	H	PHH	H+1
Pop	PHH	P	PH
None	H+1	P+1	1

eg: flowgraph



$P(PH)1 \{PCHH\}^n H P 1 (PH) 1 \{P^2 PCHH\}^m H P$

let
 M1: no. of times innerloop is taken.
 M2: no. of times Outerloop is taken.

M1	M2	Push/Pop
0	0	$P+P^2$
0	1	$P+P^2+P^3+P^4$
0	2	$\sum_{i=1}^6 P^i$
0	3	$\sum_{i=1}^8 P^i$
1	0	$1+H$
1	1	$\sum_{i=0}^3 H^i$
1	2	$\sum_{i=0}^5 H^i$
1	3	$\sum_{i=0}^7 H^i$
2	0	H^2+H^3
2	1	$\sum_{i=4}^4 H^i$
2	2	$\sum_{i=6}^6 H^i$
2	3	$\sum_{i=8}^8 H^i$

- Stack will only be popped if inner loop is not taken
- Stack will be left alone if iterated once
- for all other values of innerloop the Stack will be only pushed.

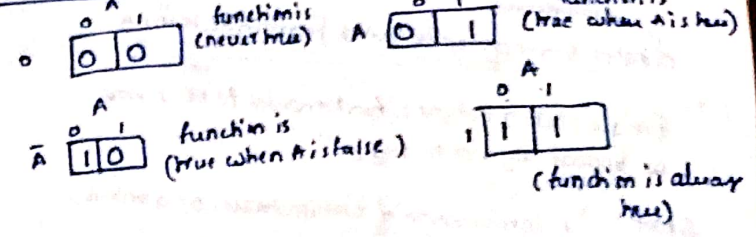
KV charts :-

If expressions in four, five, six variables, then it is tedious to deal them with algebra. So we use Karnaugh-veitch charts to reduce them graphically.

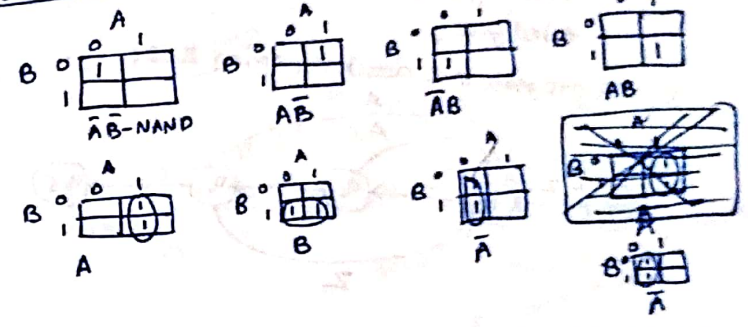
(2^{2^n}) combinations

1 → True
 0 → False

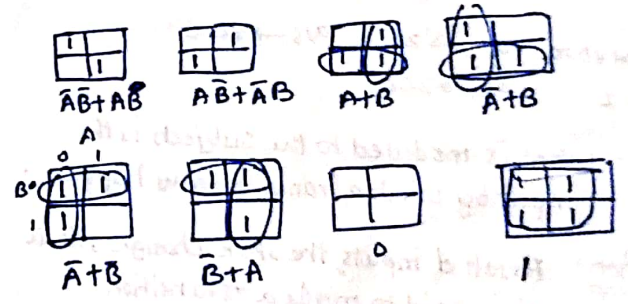
Single variable



Two variables (16 combinations (2^{2^2}))

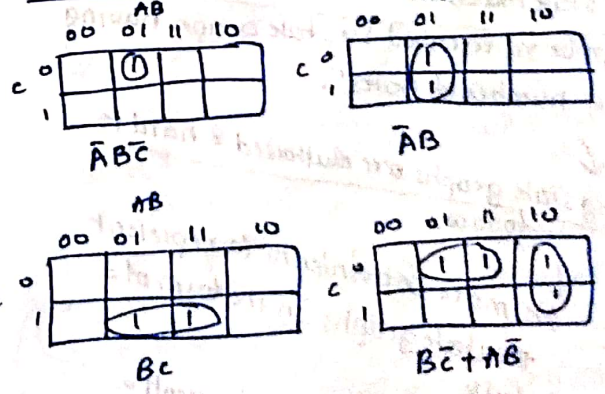


another 8 combinations



"For one variable there are $2^2 = 4$ functions, 16 functions of 2 variables - - -"

Three variables :- (give few examples)



UNIT-IX

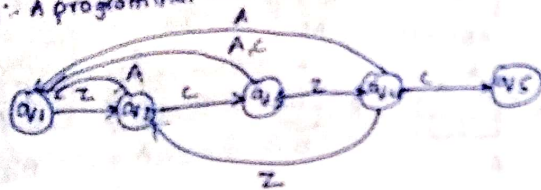
States, state graphs and Transition tables

"Finite state machine is fundamental to some as boolean algebra to logic"

State:- "A combination of circumstances or attributes belonging for time being to a person or thing"

eg: engine starts with respect to its transmission reverse gear, neutral gear, first gear, second gear, third gear.

eg: A program that detects the string ZCZC



$q_1 \rightarrow \text{None}$ $q_2 \rightarrow ZC$ $q_3 \rightarrow ZCZC$
 $q_4 \rightarrow Z$ $q_5 \rightarrow ZCZC$

Input:- what is modeled to the subjects is the input by which a transition may happen.

Transition:- Result of inputs, the state changes, then it is said to make a transition.

"There is one outlink from every state for every input"

"A finite state machine is an abstract device that can be represented by state graph having a finite number of states".

Big state graphs are cluttered & hard to follow

It's more convenient to represent the state graphs in the form of a table

where each row of table represents a state

And each column represents an input.

State	Z	C	A
None	Z	None	None
Z	Z	ZC	None
ZC	ZCZ	None	None
ZCZ	Z	ZCZC	None
ZCZC	ZCZC	ZCZC	ZCZC

"State graphs don't represent time but sequence as a transition may take a second or a century"

But in practical there is no correspondence between lines of code and states. The state table just forms the basis."

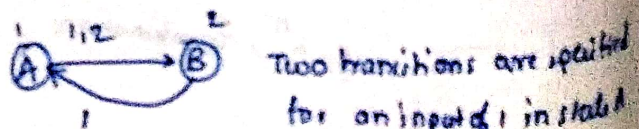
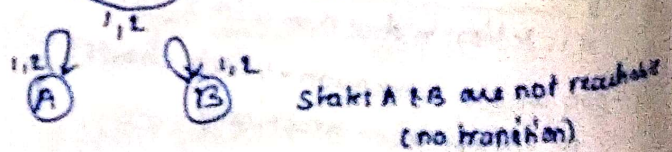
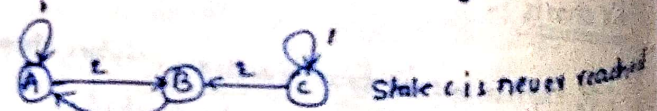
Good state graphs vs Bad state graphs

g: how to judge!

Some principles involved:-

- Total number of states = Product of possibilities that make up the state
- For every state and input only one transition to another state (possibly same state)
- For every transition there is one output action specified; The output may be trivial/maximized
- For every state there is a sequence of inputs that will drive the system back to the same state.

Important graphs:- (bad graphs)



State Bugs - number of states

- no. of states can be computed as follows
 - Identify all the component factors of a state
 - Identify all the allowable values for each factor
 - Number of states is product of number of all allowable values of all factors.

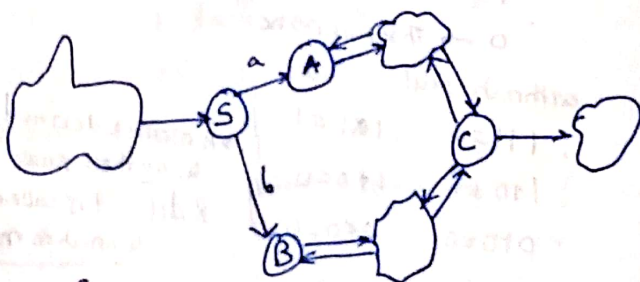
There may be a difference between developers state count and testers state count.

"A robust piece of software will not ignore impossible states but will recognize them and raise an illogical condition handler"

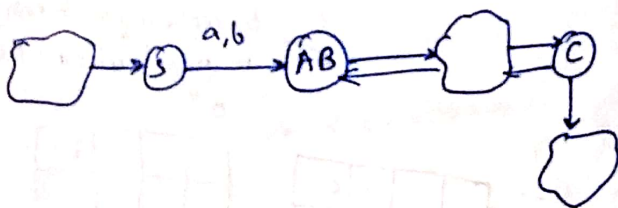
Equivalent states

"Two states are said to be equivalent if every sequence of inputs starting from one state produce same sequence of outputs when started from other side"

This notion can also be extended to set of states



Merging of equivalent states



Identifying equivalent states:

- The rows corresponding to the two states are identical with respect to input/output/next state but name of next state could differ.
- If two sets of rows have identical state graphs with respect to transitions & outputs, then they can be merged.

Transition Bugs - unspecified and contradictory Transition

- every input, state must have a transition
- If a transition is impossible, then there needs to be mechanism that prevents input from occurring in that state.
- A program can't have contradictions and ambiguities.
- Ambiguities are mostly impossible, because program does something for every input.

eg. RLW example

Unreachable states

is similar to unreachable state is not impossible

A state which no input sequence can reach (reason: incorrect transitions)

Result: 1. There is a bug
2. Transitions are there but not known

Dead states

If dead state is once entered, can never be left.
may not be a bug but should review

Output errors

wrong no. of states
wrong transitions
There may be output errors even when there are no dead, unreachable, impossible states.

unreachable states
dead states

Impact of bugs

Principles of state testing

- define a set of covering input sequences that get back to the initial state when starting from initial state
- For each step in each input sequence define expected next state, transition, output

Set of tests containing

- Input sequences
- Corresponding transitions
- output sequences

Limitations

Insisting on explicit specification of transition & output for every combination

A set of input sequences that provide coverage of all nodes & links is mandatory.

Testability tips

1. Building explicit finite state machines
2. using switches
3. using flags
4. Identifying unachievable paths
5. Identifying essential & inessential finite state behaviour
(as simple in a state it's a tip or trap)
6. Following the designing guidelines

Graph, Matrices and applications

Problem with the pictorial graphs

graphs were introduced as an abstraction of software structure

paths are used to trace and paths are subjected to errors

you can miss a link here or there or visit a link twice unknowingly

One method to avoid this problem is to represent graph as a matrix.

Tool Building

It's hard to build algorithms over visual graphs so the properties on the graph matrices are fundamental to tool building

The basic Algorithms

The basic tool consist of

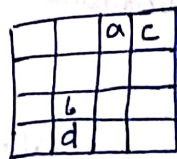
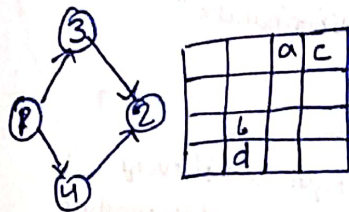
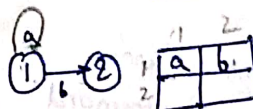
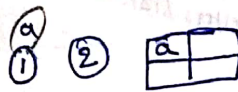
- : matrix multiplication ✓
- : Pathfinding Algorithm (to convert graphs)
- : A collapsing process (to get path expression between two nodes)

The matrix of a graph

- : "A graph matrix is a square array with one row and one column for every node in the graph".
- : Size of matrix = number of nodes ✓
- : The entry at a row & column intersection is the link weight of the link that connects the two nodes in that direction.
- : A connection from node i to j does not imply a connection from node j to i ($A \neq B$)

: If there are multiple links at a node, then + sign denotes parallel links

Some graphs & matrices



A simple weight:-

"A simple weight we can use is to note that there is or isn't a connection"

1 → There is a connection

0 → There is none

arithmetic rules:-

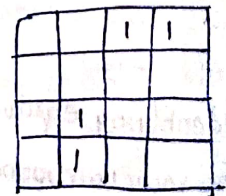
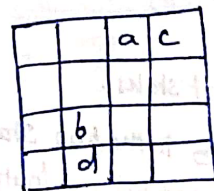
$$: 1+1=1 \quad : 1*1=1$$

$$: 1+0=1 \quad : 1*0=0$$

$$: 0+0=0 \quad : 0*0=0$$

} A matrix defined using these rules & defined is called a connection matrix

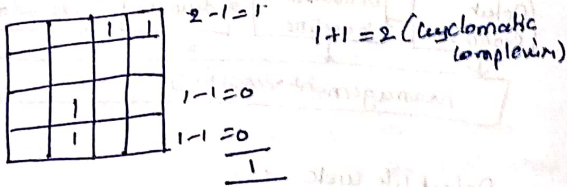
"A connection matrix is obtained by replacing each entry with 1 if there is a link, otherwise 0"



- : each row represents a outlink of the node
- : each column denotes the links corresponding to that node
- : "A branch is a node with more than one non zero entry in its row"
- : "A junction is a node with more than one non zero entry in its column"
- : "A self loop is an entry along the diagonal"

Cyclomatic Complexity

"Cyclomatic complexity is obtained by subtracting 'i' from the total number of entries in each row, ignoring rows with no entries. Then adding these values and then adding 'i' to the sum yields graphs cyclomatic complexity"



Relations:-

A relation is a property that exists between two objects of interest

→ Transitive Relations:

A relation is transitive if aRb and bRc implies

aRc

most relations used in testing are transitive

eg: \geq, \leq , faster than, slower than

eg (Intransitive): is friend of, neighbour of

→ Reflexive Relations:

A relation R is reflexive if, for every a , aRa

Reflexive relation is equivalent to a self loop at every node

ex: equals, is a relative of
eg (not reflexive) is not equal

→ Symmetric relations:

A relation R is symmetric if for every a and b , aRb implies bRa

A graph whose relations are not symmetric is called a directed graph; if symmetric undirected graph

→ Anti symmetric relations

A relation R is anti symmetric if for every a & b if aRb and bRa then $a=b$ (same elements obviously)

→ Equivalence relations

An equivalence relation is a relation that satisfies the reflexive, transitive, symmetric properties

→ if it satisfies equivalence, it can form a class

Testing a member of equivalence class is as effective as testing whole class

Partial ordering relations

A partial ordering relation satisfies the reflexive, transitive & asymmetric properties

Partial ordered graphs are loop free

The powers of a matrix

- each entry in graph's matrix expresses a relation between the pair of nodes.
- The square of matrix represents all path segments two links long.
- The third power represents all path segments three links long.

matrix powers & products:

- let a matrix a_{ij}
- then square of matrix obtained by replacing every entry with

$$a_{ij} = \sum_{k=1}^n a_{ik} a_{kj}$$

- let matrices $A_{ik} B_{kj}$ then $A \times B = C_{ij}$

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

new matrix

Partitioning algorithm

- Consider any graph over a transitive relation. The graph may have loops
- Partition such that every loop is contained within one group or another
- Such a graph is partially ordered & we might embed the loops within a subroutine
- It's much harder to program a tool recognize the loops unless you have a solid algorithm & tool.

node reduction algorithm:

"The matrix powers usually will tell us more than we want to know about graphs"

- select node for removal, replace its node by its equivalent links that bypass that node and add those links to the links they parallel.
- combine the parallel terms & simplify as far as you can
- observe loop terms and adjust the out links that have a self loop
- The result is a matrix whose size is reduced by 1. Continue until only two nodes of interest exist.

UNIT-V

Defect management

Defect → something which does not allow product to meet customer requirement

And it is cause for customer dissatisfaction

It can be

- A extra
- A missing requirement
- requirement not implemented correctly

defect is something that makes customer unhappy

Root causes of defect → defect is not an accident, but occurs but it something has not worked or planned

reasons

1. requirements not clearly defined by user
2. understanding problems is not effective
3. requirements are not resolved completely
4. designers are wrong
5. requirements & its design is different
6. Process used for development, testing are not capable

Effects of defects → The final effect of defect is customer dissatisfaction
not fit for use

due to

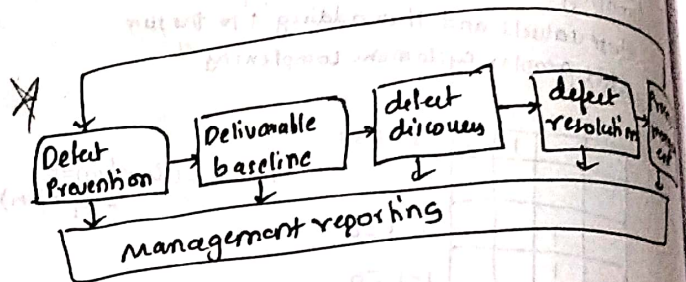
- functionality not available
- performance is not acceptable
- security issues

Defects class classification

1. requirements defects → functional defects
→ interface defects
2. Design defects → Algorithmic defects
→ module interface defects
→ System interface defects
→ User interface defects
3. coding defects → variable declaration
→ Database defects
→ documentation defects
4. Testing defects → Test design defects
→ Test environment defects
→ Test tool defects

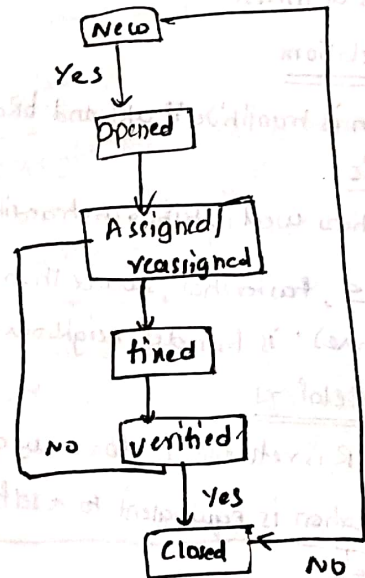
Defect management process

- primary goal is to prevent defect
- defect management must be quite driven



Defect life cycle

- Defect identified in verification/Validation must be first analyzed to check if it is defect or not.



Defect template : Every organization must have

a defect template to capture the defect

ID _____

Project _____

Product _____

Release version _____

Module _____

Defect/BUILD version _____

Summary _____

Description _____

Steps to replicate _____

Actual Result _____

Expected result _____

IPPRMDSDSA E

Attachment

Remarks

Defect severity

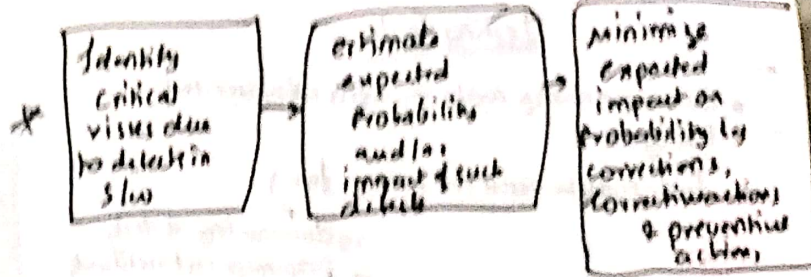
Reported by

Assigned to

Status

Fixed Build version

AR DRAC P



Finding & reporting cause of bugs

- Correction, corrective actions, preventive actions
- Defect naming: convention; named based on nature

Defect resolution

- defect fixing
- retesting
- re-saving
- Taking actions on process, methods that produced defect
- regression (to find if it has any negative effects on unchanged part of system)

Defect correction: first step to initialize when defect is found

Corrective action: identifying process, methods that caused defect

Defect prevention: prevention & updating

Delivery baselining: once defect is fixed, retested and found to be closed, the product is created again

Process improvement: continuous search to improve baseline the processes

Management reporting: maintain information flow - to and (SWOT)

Defect fixing :-

- defect must be governed by probability of happening
- Frequency & effect of a defect on user & its impact must drive defect prevention mechanism

Examples of risks

- ① Missing key requirements
- ② Applications critical part not working
- ③ Vendor supplied S/W doesn't work
- ④ S/W does not support major business functions
- ⑤ Poor performance
- ⑥ h/w malfunctioning
- ⑦ h/w or S/W do not integrate
- ⑧ user unwilling to adopt to new system

"Actual impact of defect can be measured when the risk realizes or becomes a reality in production environment". handling risks:

- > Accept risk as it is
- > Bypassing the risk

Risk minimization:

- eliminate risk
- mitigation of risk
- contingency planning

Techniques for finding defects

- static Techniques
- dynamic Techniques
- Operational Techniques

Reporting defect

- ① correct defect
- ② report system status
- ③ gather statistics
- ④ process improvement

Testing Tools

- Testers use many tools during a software-test life cycle
- Tools may be used for testing, for

→ documenting defects
→ preparing test artifacts

Software tools

- defect tracking tools
- regression testing tools
- configuration tools
- communication tools
- simulations

Hardware tools

- machines
- servers
- printers
- routers
- Any hardware simulators.

Features of test tool

- A test tool is a vehicle for performing test process & each tool has a specific purpose.
- Tools are used in SDLC

Guidelines for Selecting a tool

- The tool must match its intended use.
- matching tool with skills of tester
- affordable tools
- Backdoor entry of tools must be prevented (pirated)

Tools & skills of testers

- user skills
- programmer skills
- system skills
- technical skills

Static testing tools

- static testing tools are used during static analysis of system

Types:-

- code profiling
- data profiling
- Test data generators
- syntax-checking tools

Dynamic Testing tools

- are used ranging from unit testing to the system testing and performance testing
- Regression testing
- Defect Tracking
- Performance, load, stress testing tools

Advantages of using tools

- Tools work faster than human beings
- Tools are consistent in behaviour
- Some areas of SDLC can be only completed using tools

Disadvantages:

- wrong selection of tools may lead to disaster
- people must be trained
- cost-benefit analysis before acquiring a tool
- maintaining scripts in changing requirements may be difficult.

When to use Automated test tools

- Number of iterations & testings
- Complexity of test cases
- Test case dependency

Partial Automation :- Automating parts of testings, but not all of software testing process

Points to be remembered when thinking of test automation

- Platform & OS independence
- data driven capability
- version control is friendly
- common drivers can be used
- support distributed execution environment
- extensible test process

Framework approach in automation

☞ A framework is an integrated system that sets the rules of automation of a specified Product ☞

Synchronization

- A distributed test case consists of two or more parts, each processes on a different system that interact with each other
- Automatic synchronization
- user defined synchronization

Difficulties while introducing new tools

- ① organization obstacles
 - cost of tool
 - Training requirements
 - unwillingness to learn new skills
- ② Tool problems
- ③ Environmental problems

Process of procurement of COTS

- goals to be met
- objectives of tool
- acquisition plan
- selection criteria
- identify candidate
- user review of candidate
- score candidate
- select tool
- procure tool
- evaluation tool
- implementation plan
- Training plan
- Orientation
- Training
- evaluation report
- determine if goals met or not.

Procurement of tools from contractor

→ difference between IN-HOUSE software development & software developed by a contractor

- control over development process by vendor
- control over resources from vendor-side
- cultural differences between vendor & customer
- employee morale
- root causes of problems may not be effectively addressed by vendor

Process of procurement of tools from contractor

↑ same as above +

Request of proposal (REP) /

Request for quotation (RFQ) /

RFI (Request for information)

+

Technical evaluation

+

Acceptance testing